

Alternative Approach to Estimating the Parameters of Continuous Probability Distribution: Use of Order Statistics

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Abstract

Application of the method of moments for the parametric distribution is common in the construction of a suitable parametric distribution. However, moment method of parameter estimation does not produce good results. An alternative approach when constructing an appropriate parametric distribution for the considered data file is to use the so-called order statistics. This paper deals with the use of order statistics as the methods of L-moments and TL-moments of parameter estimation. L-moments have some theoretical advantages over conventional moments. L-moments have been introduced as a robust alternative to classical moments of probability distributions. However, L-moments and their estimations lack some robust features that belong to the TL-moments. TL-moments represent an

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alternative robust version of L-moments, which are called trimmed L-moments. This paper deals with the use of L-moments and TL-moments in the construction of models of wage distribution. Three-parametric lognormal curves represent the basic theoretical distribution whose parameters were simultaneously estimated by three methods of point parameter estimation and accuracy of these methods was then evaluated. There are method of TL-moments, method of L-moments and maximum likelihood method in combination with Cohen's method. A total of 328 wage distribution has been the subject of research.

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1 L-Moments

Moments and cumulants are traditionally used to characterize the probability distribution or the observed data set in statistics. It is sometimes difficult to determine exactly what information about the shape of the distribution is expressed by its moments of third and higher order. Especially in the case of a small sample, numerical values of sample moments can be very different from the values of theoretical moments of the probability distribution from which the random sample comes. Particularly in the case of small samples, parameter estimations of the probability distribution obtained using the moment method are often markedly less accurate than estimates obtained using other methods, such as maximum likelihood method.

An alternative approach is to use the order statistics. Let X be a random variable having a distribution with distribution function $F(x)$ and with quantile

function $x(F)$, and let X_1, X_2, \dots, X_n is a random sample of sample size n from this distribution. Then $X_{1:n} \leq X_{2:n} \leq \dots \leq X_{n:n}$ are the order statistics of random sample of sample size n , which comes from the distribution of random variable X .

L-moments are analogous to conventional moments and are estimated based on linear combinations of order statistics, i.e. L-statistics. L-moments are an alternative system describing the shape of the probability distribution.

L-moments present the basis for a general theory, which includes the characterization and description of the theoretical probability distribution, characterization and description of the obtained sample data sets, parameter estimation of theoretical probability distribution and hypothesis testing of parameter values for the theoretical probability distribution. The theory of L-moments includes such established procedures such as the use of order statistics and Gini's middle difference and leads to some promising innovations in the area of measuring skewness and kurtosis of the distribution and provides relatively new methods of parameter estimation for individual distribution. L-moments can be defined for any random variable whose expected value exists. The main advantage of the L-moments than conventional moments consists in the fact that L-moments can be estimated on the basis of linear functions of the data and are more resistant to the influence of sample variation. Compared to conventional moments, L-moments are more robust to the existence of outliers in the data and allow better conclusions obtained on the basis of small samples for basic probability distribution. L-moments often bring even more efficient parameter estimations of parametric distribution than the estimations obtained using maximum likelihood method, especially for small samples. Theoretical advantages of L-moments over conventional moments lie in the ability to characterize a wider range of distribution and in greater resistance to the presence of outliers in the data when estimating from the sample. Compared with conventional moments, experience also shows that L-moments are less prone to bias estimation and approximation by asymptotic normal distribution is more accurate in finite samples.

1.1 L-Moments of Probability Distribution

Let X be a continuous random variable that has a distribution with distribution function $F(x)$ and with quantile function $x(F)$. Let $X_{1:n} \leq X_{2:n} \leq \dots \leq X_{n:n}$ are the order statistics of random sample of sample size n , which comes from the distribution of random variable X . L-moment of the r -th order of random variable X is defined

$$\lambda_r = \frac{1}{r} \cdot \sum_{j=0}^{r-1} (-1)^j \cdot \binom{r-1}{j} \cdot E(X_{r-j:r}), \quad r=1, 2, \dots \quad (1)$$

Expected value of the r -th order statistic of random sample of sample size n has the form

$$E(X_{r:n}) = \frac{n!}{(r-1)! \cdot (n-r)!} \cdot \int_0^1 x(F) \cdot [F(x)]^{r-1} \cdot [1-F(x)]^{n-r} dF(x). \quad (2)$$

If we substitute equation (2) into equation (1), we obtain after adjustments

$$\lambda_r = \int_0^1 x(F) \cdot P_{r-1}^*[F(x)] dF(x), \quad r=1, 2, \dots, \quad (3)$$

where

$$P_r^*[F(x)] = \sum_{j=0}^r p_{r,j}^* \cdot [F(x)]^j \quad \text{a} \quad p_{r,j}^* = (-1)^{r-j} \cdot \binom{r}{j} \cdot \binom{r+j}{j}, \quad (4)$$

and $P_r^*[F(x)]$ represents the r -th shifted Legendre polynomial. We also obtain substituting (2) into equation (1)

$$\lambda_r = \frac{1}{r} \cdot \sum_{j=0}^{r-1} (-1)^j \cdot \binom{r-1}{j} \cdot \frac{r!}{(r-j-1)! \cdot j!} \cdot \int_0^1 x(F) \cdot [F(x)]^{r-j-1} \cdot [1-F(x)]^j dF(x), \quad r=1, 2, \dots \quad (5)$$

The letter ‘‘L’’ in the name of ‘‘L-moments’’ stresses that the r -th L-moment λ_r is a linear function of the expected value of certain linear combination of order statistics. Own estimation of the r -th L-moment λ_r based on the obtained data sample is then linear combination of ordered sample values, i.e. L-statistics. The

first four L-moments of the probability distribution in now defined

$$\lambda_1 = E(X_{1:1}) = \int_0^1 x(F) \, dF(x), \quad (6)$$

$$\lambda_2 = \frac{1}{2} E(X_{2:2} - X_{1:2}) = \int_0^1 x(F) \cdot [2F(x) - 1] \, dF(x), \quad (7)$$

$$\lambda_3 = \frac{1}{3} E(X_{3:3} - 2X_{2:3} + X_{1:3}) = \int_0^1 x(F) \cdot \{6[F(x)]^2 - 6F(x) + 1\} \, dF(x), \quad (8)$$

$$\begin{aligned} \lambda_4 &= \frac{1}{4} E(X_{4:4} - 3X_{3:4} + 3X_{2:4} - X_{1:4}) \\ &= \int_0^1 x(F) \cdot \{20[F(x)]^3 - 30[F(x)]^2 + 12[F(x)] - 1\} \, dF(x). \end{aligned} \quad (9)$$

The probability distribution can be specified by its L-moments, even if some its conventional moments do not exist, but the opposite is not true. It can be proved that the first L-moment λ_1 is the level characteristic of the probability distribution, the second L-moment λ_2 is the variability characteristic, of a random variable X . It is convenient to standardize the higher L-moments λ_r , $r \geq 3$, to be independent on specific units of the random variable X . The ratio of L-moments of the r -th order of random variable X is defined

$$\tau_r = \frac{\lambda_r}{\lambda_2}, \quad r = 3, 4, \dots \quad (10)$$

It is also possible to define such a function of L-moments, which is analogous to the classical coefficient of variation, i.e. the so-called L-coefficient of variation.

$$\tau = \frac{\lambda_2}{\lambda_1}. \quad (11)$$

Table 1: Formulas for the distribution function or quantile function, and for L-moments and ratios of L-moments of chosen probability distributions

Distribution	Distribution function $F(x)$ or quantile function $x(F)$	L-moments and ratios of L-moments
Uniform	$x(F) = \alpha + (\beta - \alpha) \cdot F(x)$	$\lambda_1 = \frac{\alpha + \beta}{2}$ $\lambda_2 = \frac{\beta - \alpha}{6}$ $\tau_3 = 0$ $\tau_4 = 0$
Exponential	$x(F) = \xi - \alpha \cdot \ln[1 - F(x)]$	$\lambda_1 = \xi + \alpha$ $\lambda_2 = \frac{\alpha}{2}$ $\tau_3 = \frac{1}{3}$ $\tau_4 = \frac{1}{6}$
Gumbel	$x(F) = \xi - \alpha \cdot \ln[-\ln F(x)]$	$\lambda_1 = \xi + e \cdot \alpha$ $\lambda_2 = \alpha \cdot \ln 2$ $\tau_3 = 0,1699$ $\tau_4 = 0,1504$
Logistic	$x(F) = \xi + \alpha \cdot \ln \frac{F(x)}{1 - F(x)}$	$\lambda_1 = \xi$ $\lambda_2 = \alpha$ $\tau_3 = 0$ $\tau_4 = \frac{1}{6}$

Source: Hosking (1990); own research

Table 1: Continuation

Distribution	Distribution function $F(x)$ or quantile function $x(F)$	L-moments and ratios of L-moments
Normal	$F(x) = \Phi \left[\frac{x(F) - \mu}{\sigma} \right]$	$\lambda_1 = \mu$ $\lambda_2 = \pi^{-1} \cdot \sigma$ $\tau_3 = 0$ $\tau_4 = 30 \cdot \pi^{-1} \cdot (\tan \sqrt{2})^{-1} - 9 = 0,1226$
Generalized Pareto	$x(F) = \xi + \alpha \cdot \frac{1 - [1 - F(x)]^k}{k}$	$\lambda_1 = \xi + \frac{\alpha}{1 + k}$ $\lambda_2 = \frac{\alpha}{(1 + k) \cdot (2 + k)}$ $\tau_3 = \frac{1 - k}{3 + k}$ $\tau_4 = \frac{(1 - k) \cdot (2 - k)}{(3 + k) \cdot (4 + k)}$
Generalized extreme value	$x(F) = \xi + \alpha \cdot \frac{1 - [-\ln F(x)]^k}{k}$	$\lambda_1 = \xi + \alpha \cdot \frac{1 - \Gamma(1 + k)}{k}$ $\lambda_2 = \alpha \cdot \frac{(1 - 2^{-k}) \cdot \Gamma(1 + k)}{k}$ $\tau_3 = \frac{2 \cdot (1 - 3^{-k})}{1 - 2^{-k}} - 3$ $\tau_4 = \frac{1 - 6,2^{-k} + 10,3^{-k} - 5,4^{-k}}{1 - 2^{-k}}$
Generalized logistic	$x(F) = \xi + \alpha \cdot \frac{1 - \left[\frac{1 - F(x)}{F(x)} \right]^k}{k}$	$\lambda_1 = \xi + \alpha \cdot \frac{1 - \Gamma(1 + k) \cdot \Gamma(1 - k)}{k}$ $\lambda_2 = \alpha \cdot \Gamma(1 + k) \cdot \Gamma(1 - k)$ $\tau_3 = -k$ $\tau_4 = (1 + 5k^2) / 6$

Table 1: Continuation

Distribution	Distribution function $F(x)$ or quantile function $x(F)$	L-moments and ratios of L-moments
Lognormal	$F(x) = \Phi \left\{ \frac{\ln[x(F) - \xi] - \mu}{\sigma} \right\}$	$\lambda_1 = \xi + \exp \left(\mu + \frac{\sigma^2}{2} \right)$ $\lambda_2 = \exp \left(\mu + \frac{\sigma^2}{2} \right) \cdot \operatorname{erf} \left(\frac{\sigma}{2} \right)$ $\tau_3 = 6 \pi^{\frac{1}{2}} \cdot \frac{\int_0^{\frac{\sigma}{2}} \operatorname{erf} \left(\frac{x}{\sqrt{3}} \right) \cdot \exp(-x^2) dx}{\operatorname{erf} \left(\frac{\sigma}{2} \right)}$
Generalized logistic	$x(F) = \xi + \alpha \cdot \frac{1 - \left[\frac{1 - F(x)}{F(x)} \right]^k}{k}$	$\lambda_1 = \xi + \alpha \cdot \frac{1 - \Gamma(1+k) \cdot \Gamma(1-k)}{k}$ $\lambda_2 = \alpha \cdot \Gamma(1+k) \cdot \Gamma(1-k)$ $\tau_3 = -k$ $\tau_4 = \frac{1 + 5k^2}{6}$
Gamma	$F(x) = \frac{\beta^{-\alpha}}{\Gamma(\alpha)} \cdot \int_0^{x(F)} t^{\alpha-1} \cdot \exp \left(-\frac{t}{\beta} \right) dt$	$\lambda_1 = \alpha \cdot \beta$ $\lambda_2 = \pi^{\frac{1}{2}} \cdot \beta \cdot \frac{\Gamma \left(\alpha + \frac{1}{2} \right)}{\Gamma(\alpha)}$ $\tau_3 = 6 I_{\frac{1}{3}}(\alpha, 2\alpha) - 3^{1)}$

Source: Hosking (1990); own research

The ratio of L-moments τ_3 is the skewness characteristic and the ratio of

¹⁾ $I_x(p, q)$ is incomplete beta function

L-moments τ_4 is the kurtosis characteristic of the corresponding probability distribution. Main properties of the probability distribution are summarized very well by the following four characteristics: L-location λ_1 , L-variation λ_2 , L-skewness τ_3 and L-kurtosis τ_4 . L-moments λ_1 and λ_2 , L-coefficient of variation τ and ratios of L-moments τ_3 and τ_4 are the most useful measurements for characterizing the probability distribution. Their most important features are: the existence (if the expected value of the distribution exists, then all L-moments of the distribution exist, too) and uniqueness (if the expected value of the distribution exists, then L-moments define only one distribution, i.e. no two distributions have the same L-moments).

Using equations (6)–(9) and equation (10) we obtain formulas for L-moments, respectively for the ratios of L-moments for the case of chosen probability distributions, see Table 1. More on the L-moments is for example in [13], [14], [17] and [21].

1.2 Sample L-Moments

We usually estimate L-moments using random sample, which is taken from an unknown distribution. Since the r -th L-moment λ_r is a function of the expected values of order statistics of random sample of sample size r , it is natural to estimate it using the so-called U-statistic, i.e. the corresponding function of sample order statistics (averaged over partial subsets of sample size r , which can be formed from the obtained random sample of sample size n).

Let x_1, x_2, \dots, x_n is a sample and $x_{1:n} \leq x_{2:n} \leq \dots \leq x_{n:n}$ is an ordered sample. Then the r -th sample L-moment can be written as

$$l_r = \binom{n}{r}^{-1} \sum_{1 \leq i_1 < i_2 < \dots < i_r \leq n} \frac{1}{r} \sum_{j=0}^{r-1} (-1)^j \binom{r-1}{j} \cdot x_{i_{r-j}}, \quad r=1, 2, \dots, n. \quad (12)$$

Hence the first four sample L-moments have the form

$$l_1 = \frac{1}{n} \cdot \sum_i x_i, \quad (13)$$

$$l_2 = \frac{1}{2} \cdot \binom{n}{2}^{-1} \cdot \sum_{i>j} (x_{i:n} - x_{j:n}), \quad (14)$$

$$l_3 = \frac{1}{3} \cdot \binom{n}{3}^{-1} \cdot \sum_{i>j>k} (x_{i:n} - 2x_{j:n} + x_{k:n}), \quad (15)$$

$$l_4 = \frac{1}{4} \cdot \binom{n}{4}^{-1} \cdot \sum_{i>j>k>l} (x_{i:n} - 3x_{j:n} + 3x_{k:n} - x_{l:n}). \quad (16)$$

U-statistics are widely used especially in nonparametric statistics. Their positive features are: the absence of bias, asymptotic normality and some slight resistance due to the influence of outliers.

When calculating the r -th sample L-moment it is not necessary to repeat the calculation across all partial subsets of sample size r , but this statistic can be expressed directly as linear combination of order statistics of random sample of sample size n . If we consider the estimation of $E(X_{r:r})$, which is taken using U-statistics, this estimate can be written as $r \cdot b_{r-1}$, where

$$b_r = \frac{1}{n} \cdot \binom{n-1}{r}^{-1} \cdot \sum_{j=r+1}^n \binom{j-1}{r} \cdot x_{j:n}, \quad (17)$$

specifically

$$b_0 = \frac{1}{n} \cdot \sum_{j=1}^n x_{j:n}, \quad (18)$$

$$b_1 = \frac{1}{n} \cdot \sum_{j=2}^n \frac{(j-1)}{(n-1)} \cdot x_{j:n}, \quad (19)$$

$$b_2 = \frac{1}{n} \cdot \sum_{j=3}^n \frac{(j-1) \cdot (j-2)}{(n-1) \cdot (n-2)} \cdot x_{j:n}, \quad (20)$$

therefore generally

$$b_r = \frac{1}{n} \cdot \sum_{j=r+1}^n \frac{(j-1) \cdot (j-2) \cdot \dots \cdot (j-r)}{(n-1) \cdot (n-2) \cdot \dots \cdot (n-r)} \cdot X_{j:n}. \quad (21)$$

Therefore the first sample L-moments can be written as

$$l_1 = b_0, \quad (22)$$

$$l_2 = 2b_1 - b_0, \quad (23)$$

$$l_3 = 6b_2 - 6b_1 + b_0, \quad (24)$$

$$l_4 = 20b_3 - 30b_2 + 12b_1 - b_0. \quad (25)$$

Thus, we can write universally

$$l_{r+1} = \sum_{k=0}^r p_{r,k}^* \cdot b_k, \quad r=0, 1, \dots, n-1, \quad (26)$$

where

$$p_{r,k}^* = (-1)^{r-k} \cdot \binom{r}{k} \cdot \binom{r+k}{k} = \frac{(-1)^{r-k} \cdot (r+k)!}{(k!)^2 \cdot (r-k)!}. \quad (27)$$

Application of sample L-moments is similar to the application of sample conventional moments. Sample L-moments summarize the basic properties of the sample distribution, which are the location (level), variability, skewness and kurtosis. Thus, sample L-moments estimate the corresponding properties of the probability distribution from which the sample comes and can be used in estimating the parameters of the relevant theoretical probability distribution. Under such applications, we often prefer the L-moments before conventional moments, since as a linear function of data, sample L-moments are less sensitive to the sample variability than conventional moments or to the size of errors in the case of existence of outliers. L-moments therefore lead to more accurate and

robust estimations of the parameters or characteristics of a basic probability distribution, see for example [1]–[8] or [11].

Sample L-moments were used already previously in the statistics, although not as a part of a unified theory. The first sample L-moment l_1 is a sample L-location (sample average), the second sample L-moment l_2 is a sample L-variability.

Table 2: Formulas for estimations of parameters taken by the method of L-moments of chosen probability distributions

Distribution	Parameter estimation
Exponential	(ξ known) $\hat{\alpha} = l_1$
Gumbel	$\hat{\alpha} = \frac{l_2}{\ln 2}$ $\hat{\xi} = l_1 - e \cdot \hat{\alpha}$
Logistic	$\hat{\alpha} = l_2$ $\hat{\xi} = l_1$
Normal	$\hat{\sigma} = \pi^{\frac{1}{2}} \cdot l_2$ $\hat{\mu} = l_1$
Generalized Pareto	(ξ known) $\hat{k} = \frac{l_1}{l_2} - 2$ $\hat{\alpha} = (1 + \hat{k}) \cdot l_1$

Source: Hosking (1990); own research

Table 2: Continuation

Distribution	Parameter estimation
Generalized extreme value	$z = \frac{2}{3 + t_3} - \frac{\ln 2}{\ln 3}$
	$\hat{k} = 7,8590z + 2,9554z^2$
	$\hat{\alpha} = \frac{l_2 \cdot \hat{k}}{(1 - 2^{-\hat{k}}) \cdot \Gamma(1 + \hat{k})}$
	$\hat{\xi} = l_1 + \hat{\alpha} \cdot \frac{\Gamma(1 + \hat{k}) - 1}{\hat{k}}$
Generalized logistic	$\hat{k} = -t_3$
	$\hat{\alpha} = \frac{l_2}{\Gamma(1 + \hat{k}) \cdot \Gamma(1 - \hat{k})}$
	$\hat{\xi} = l_1 + \frac{l_2 - \hat{\alpha}}{\hat{k}}$
Lognormal	$z = \sqrt{\frac{8}{3}} \cdot \Phi^{-1}\left(\frac{1 + t_3}{2}\right)^2$
	$\hat{\sigma} = 0,999\,281z - 0,006\,118z^3 + 0,000\,127z^5$
	$\hat{\mu} = \ln \frac{l_2}{\operatorname{erf}\left(\frac{\sigma}{2}\right)} - \frac{\hat{\sigma}^2}{2}$
	$\hat{\xi} = l_1 - \exp\left(\hat{\mu} + \frac{\hat{\sigma}^2}{2}\right)$

Source: Hosking (1990); own research

²⁾ $\Phi^{-1}(\cdot)$ is quantile function of standardized normal distribution

Table 2: Continuation

Distribution	Parameter estimation
	(ξ known)
	$t = \frac{l_2}{l_1}$
	if $0 < t < \frac{1}{2}$, then :
	$z = \pi \cdot t^2$
	$\hat{\alpha} \approx \frac{1 - 0,3080 z}{z - 0,05812 z^2 + 0,01765 z^3}$
Gamma	
	if $\frac{1}{2} \leq t < 1$, then :
	$z = 1 - t$
	$\hat{\alpha} \approx \frac{0,7213 z - 0,5947 z^2}{1 - 2,1817 z + 1,2113 z^2}$
	$\hat{\beta} = \frac{l_1}{\hat{\alpha}}$

Source: Hosking (1990); own research

Natural estimation of the ratio of L-moments (10) is the sample ratio of L-moments

$$t_r = \frac{l_r}{l_2}, \quad r = 3, 4, \dots \quad (28)$$

Hence t_3 is a sample L-skewness and t_4 is a sample L-kurtosis. Sample ratios of L-moments t_3 and t_4 can be used as characteristics of skewness and kurtosis of the sample data file. Gini's middle difference is related to sample L-moments, which has the form

$$G = \binom{n}{2}^{-1} \cdot \sum_{i>j} (x_{i:n} - x_{j:n}), \quad (29)$$

and Gini's coefficient, which depends only on a single parameter σ in the case of two-parametric lognormal distribution, but it depends on the values of all three parameters in the case of three-parametric lognormal distribution. Table 2 presents the formulas for estimation of parameters of chosen probability distributions, which were obtained using the method of L-moments.

2 TL-Moments

Alternative robust version of L-moments will be now presented. This robust modification of L-moments is called „trimmed L-moments“, and labeled „TL-moments“.

This is a relatively new category of moment characteristics of the probability distribution. There are the characteristics of the level, variability, skewness and kurtosis of probability distributions constructed using TL-moments that are robust extending of L-moments. L-moments alone were introduced as a robust alternative to classical moments of probability distributions. However, L-moments and their estimations lack some robust properties that belong to the TL-moments.

Sample TL-moments are linear combinations of sample order statistics, which assign zero weight to a predetermined number of sample outliers. Sample TL-moments are unbiased estimations of the corresponding TL-moments of probability distributions. Some theoretical and practical aspects of TL-moments are still under research or remain for future research. Efficiency of TL-statistics depends on the choice of α proportion, for example, the first sample TL-moments $l_1^{(0)}, l_1^{(1)}, l_1^{(2)}$ have the smallest variance (the highest efficiency) among other estimations from random samples from normal, logistic and double exponential distribution.

When constructing the TL-moments, the expected values of order statistics of random sample in the definition of L-moments of probability distributions are replaced by the expected values of order statistics of a larger random sample, where the sample size grows like this, so that it will correspond to the total size of modification, as shown below.

TL-moments have certain advantages over conventional L-moments and central moments. TL-moment of probability distribution may exist even if the corresponding L-moment or central moment of the probability distribution does not exist, as it is the case of Cauchy's distribution. Sample TL-moments are more resistant to existence of outliers in the data. The method of TL-moments is not intended to replace the existing robust methods, but rather as their supplement, especially in situations where we have outliers in the data.

2.1 TL-Moments of Probability Distribution

In this alternative robust modification of L-moments, the expected value $E(X_{r-j:r})$ is replaced by the expected value $E(X_{r+t_1-j:r+t_1+t_2})$. Thus, for each r we increase sample size of random sample from the original r to $r + t_1 + t_2$ and we work only with the expected values of these r treated order statistics $X_{t_1+1:r+t_1+t_2}, X_{t_1+2:r+t_1+t_2}, \dots, X_{t_1+r:r+t_1+t_2}$ by trimming the t_1 smallest and the t_2 largest from the conceptual sample. This modification is called the r -th trimmed L-moment (TL-moment) and is marked $\lambda_r^{(t_1, t_2)}$. Thus, TL-moment of the r -th order of random variable X is defined

$$\lambda_r^{(t_1, t_2)} = \frac{1}{r} \cdot \sum_{j=0}^{r-1} (-1)^j \cdot \binom{r-1}{j} \cdot E(X_{r+t_1-j:r+t_1+t_2}), \quad r = 1, 2, \dots \quad (30)$$

It is apparent from equations (30) and (1) that the TL-moments simplify to L-moments, when $t_1 = t_2 = 0$. Although we can also consider applications, where the values of trimming are not equal, i.e. $t_1 \neq t_2$, we focus here only on symmetric case $t_1 = t_2 = t$. Then equation (30) can be rewritten

$$\lambda_r^{(t)} = \frac{1}{r} \cdot \sum_{j=0}^{r-1} (-1)^j \cdot \binom{r-1}{j} \cdot E(X_{r+t-j:r+2t}), \quad r = 1, 2, \dots \quad (31)$$

Thus, for example, $\lambda_1^{(t)} = E(X_{1+t:1+2t})$ is the expected value of median from conceptual random sample of sample size $1 + 2t$. It is necessary here to note that $\lambda_1^{(t)}$ is equal to zero for distributions, which are symmetrical around zero.

First four TL-moments have the form for $t = 1$

$$\lambda_1^{(1)} = E(X_{2:3}), \quad (32)$$

$$\lambda_2^{(1)} = \frac{1}{2} E(X_{3:4} - X_{2:4}), \quad (33)$$

$$\lambda_3^{(1)} = \frac{1}{3} E(X_{4:5} - 2X_{3:5} + X_{2:5}), \quad (34)$$

$$\lambda_4^{(1)} = \frac{1}{4} E(X_{5:6} - 3X_{4:6} + 3X_{3:6} - X_{2:6}). \quad (35)$$

Note that the measures of location (level), variability, skewness and kurtosis of the probability distribution analogous to conventional L-moments (6)–(9) are based on $\lambda_1^{(1)}$, $\lambda_2^{(1)}$, $\lambda_3^{(1)}$ and $\lambda_4^{(1)}$.

Expected value $E(X_{r:n})$ can be written using the formula (2). Using equation (2) we can re-express the right side of equation (31)

$$\lambda_r^{(t)} = \frac{1}{r} \cdot \sum_{j=0}^{r-1} (-1)^j \cdot \binom{r-1}{j} \cdot \frac{(r+2t)!}{(r+t-j-1)! \cdot (t+j)!} \cdot \int_0^1 x(F) \cdot [F(x)]^{r+t-j-1} \cdot [1-F(x)]^{t+j} dF(x), \quad (36)$$

It is necessary to be noted here that $\lambda_r^{(0)} = \lambda_r$ is a normal the r -th L-moment without any trimming.

Expressions (32)–(35) for the first four TL-moments, where $t = 1$, can be written in an alternative manner

$$\lambda_1^{(1)} = 6 \cdot \int_0^1 x(F) \cdot [F(x)] \cdot [1-F(x)] dF(x), \quad (37)$$

$$\lambda_2^{(1)} = 6 \cdot \int_0^1 x(F) \cdot [F(x)] \cdot [1 - F(x)] \cdot [2F(x) - 1] dF(x), \quad (38)$$

$$\lambda_3^{(1)} = \frac{20}{3} \cdot \int_0^1 x(F) \cdot [F(x)] \cdot [1 - F(x)] \cdot \{5[F(x)]^2 - 5F(x) + 1\} dF(x), \quad (39)$$

$$\lambda_4^{(1)} = \frac{15}{2} \cdot \int_0^1 x(F) \cdot [F(x)] \cdot [1 - F(x)] \cdot \{14[F(x)]^3 - 21[F(x)]^2 + 9[F(x)] - 1\} dF(x). \quad (40)$$

Distribution may be identified by its TL-moments, although some of its L-moments or conventional central moments do not exist; for example $\lambda_1^{(1)}$ (expected value of median of conceptual random sample of sample size three) exists for Cauchy's distribution, although the first L-moment λ_1 does not exist.

TL-skewness $\tau_3^{(t)}$ and TL-kurtosis $\tau_4^{(t)}$ are defined analogously as L-skewness τ_3 and L-kurtosis τ_4

$$\tau_3^{(t)} = \frac{\lambda_3^{(t)}}{\lambda_2^{(t)}}, \quad (41)$$

$$\tau_4^{(t)} = \frac{\lambda_4^{(t)}}{\lambda_2^{(t)}}. \quad (42)$$

2.2 Sample TL-Moments

Let x_1, x_2, \dots, x_n is a sample and $x_{1:n} \leq x_{2:n} \leq \dots \leq x_{n:n}$ is an ordered sample.

Expression

$$\hat{E}(X_{j+1:j+l+1}) = \frac{1}{\binom{n}{j+l+1}} \cdot \sum_{i=1}^n \binom{i-1}{j} \cdot \binom{n-i}{l} \cdot x_{i:n} \quad (43)$$

is considered to be an unbiased estimation of expected value of the $(j + 1)$ -th order statistic $X_{j+1:j+l+1}$ in conceptual random sample of sample size $(j + l + 1)$. Now we will assume that we replace the expression $E(X_{r+t-j:r+2t})$ by its unbiased estimation in the definition of the r -th TL-moment $\lambda_r^{(t)}$ in (31)

$$\hat{E}(X_{r+t-j:r+2t}) = \frac{1}{\binom{n}{r+2t}} \cdot \sum_{i=1}^n \binom{i-1}{r+t-j-1} \cdot \binom{n-i}{t+j} \cdot x_{i:n}, \quad (44)$$

which we gain by assigning $j \rightarrow r + t - j - 1$ a $l \rightarrow t + j$ in (43). Now we obtain the r -th sample TL-moment

$$l_r^{(t)} = \frac{1}{r} \cdot \sum_{j=0}^{r-1} (-1)^j \cdot \binom{r-1}{j} \cdot \hat{E}(X_{r+t-j:r+2t}), \quad r = 1, 2, \dots, n - 2t, \quad (45)$$

i.e.

$$l_r^{(t)} = \frac{1}{r} \cdot \sum_{j=0}^{r-1} (-1)^j \cdot \binom{r-1}{j} \cdot \frac{1}{\binom{n}{r+2t}} \cdot \sum_{i=1}^n \binom{i-1}{r+t-j-1} \cdot \binom{n-i}{t+j} \cdot x_{i:n}, \quad r = 1, 2, \dots, n - 2t, \quad (46)$$

which is unbiased estimation of the r -th TL-moment $\lambda_r^{(t)}$. Note that for each $j = 0, 1, \dots, r - 1$, values $x_{i:n}$ in (46) are nonzero only for $r + t - j \leq i \leq n - t - j$ due to the combinatorial numbers. Simple adjustment of the equation (46) provides an alternative linear form

$$l_r^{(t)} = \frac{1}{r} \cdot \sum_{i=r+t}^{n-t} \left[\frac{\sum_{j=0}^{r-1} (-1)^j \cdot \binom{r-1}{j} \binom{i-1}{r+t-j-1} \cdot \binom{n-i}{t+j}}{\binom{n}{r+2t}} \right] \cdot x_{i:n}. \quad (47)$$

For example, we obtain for $r = 1$ for the first sample TL-moment

$$l_1^{(t)} = \sum_{i=t+1}^{n-t} w_{i:n}^{(t)} \cdot x_{i:n}, \quad (48)$$

where the weights are given by

$$w_{i:n}^{(t)} = \frac{\binom{i-1}{t} \cdot \binom{n-i}{t}}{\binom{n}{2t+1}}. \quad (49)$$

Table 3: Formulas for TL-moments and ratios of TL-moments and formulas for estimations of parameters taken by the method of TL-moments of chosen probability distributions ($t = 1$)

Distribution	TL-moments and ratios of	
	TL-moments	Parameter estimation
Normal	$\lambda_1^{(1)} = \mu$	$\hat{\mu} = l_1^{(1)}$ $\hat{\sigma} = \frac{l_2^{(1)}}{0,297}$
	$\lambda_2^{(1)} = 0,297 \sigma$	
	$\tau_3^{(1)} = 0$	
	$\tau_4^{(1)} = 0,062$	
Logistic	$\lambda_1^{(1)} = \mu$	$\hat{\mu} = l_1^{(1)}$ $\hat{\sigma} = 2l_2^{(1)}$
	$\lambda_2^{(1)} = 0,500 \sigma$	
	$\tau_3^{(1)} = 0$	
	$\tau_4^{(1)} = 0,083$	
Cauchy	$\lambda_1^{(1)} = \mu$	$\hat{\mu} = l_1^{(1)}$ $\hat{\sigma} = \frac{l_2^{(1)}}{0,698}$
	$\lambda_2^{(1)} = 0,698 \sigma$	
	$\tau_3^{(1)} = 0$	
	$\tau_4^{(1)} = 0,343$	
	$\lambda_1^{(1)} = \frac{5\alpha}{6}$	

	$\lambda_2^{(1)} = \frac{\alpha}{4}$	
Exponential	$\tau_3^{(1)} = \frac{2}{9}$	$\hat{\alpha} = \frac{6l_1^{(1)}}{5}$
	$\tau_4^{(1)} = \frac{1}{12}$	

Source: Elamir & Seheult (2003); own research

The above results can be used to estimate TL-skewness and TL-kurtosis by simple ratios

$$t_3^{(t)} = \frac{l_3^{(t)}}{l_2^{(t)}}, \quad (50)$$

$$t_4^{(t)} = \frac{l_4^{(t)}}{l_2^{(t)}}. \quad (51)$$

We can choose $t = n\alpha$ representing the amount of the adjustment from each end of the sample, where α is a certain proportion, where $0 \leq \alpha < 0,5$.

Table 3 contains the formulas for TL-moments and for the ratios of TL-moments and the formulas for parameter estimations obtained using the method of TL-moments of chosen probability distributions. More on the TL-moments is for example in [12].

3 Lognormal Curves

3.1 Three-Parametric Lognormal Curves

Random variable X has three-parametric lognormal distribution with parameters μ , σ^2 and θ , where $-\infty < \mu < \infty$, $\sigma^2 > 0$, $-\infty < \theta < \infty$, if its probability density function have the form

$$\begin{aligned}
 f(x; \mu, \sigma^2, \theta) &= \frac{1}{\sigma \cdot (x - \theta) \cdot \sqrt{2\pi}} \cdot \exp\left[-\frac{[\ln(x - \theta) - \mu]^2}{2\sigma^2}\right], & x > \theta, \\
 &= 0, & \text{else.}
 \end{aligned} \tag{52}$$

Lognormal distribution with parameters μ , σ^2 and θ (beginning of distribution, theoretical minimum) is marked $\text{LN}(\mu, \sigma^2, \theta)$. Probability density function of three-parametric lognormal distribution is asymmetric, positively skewed. Figures 1 and 2 show the graphs of the probability density function of three-parametric lognormal distribution depending on the values of the parameters of this distribution.

Probability density function of three-parametric lognormal distribution is sometimes presented in the form

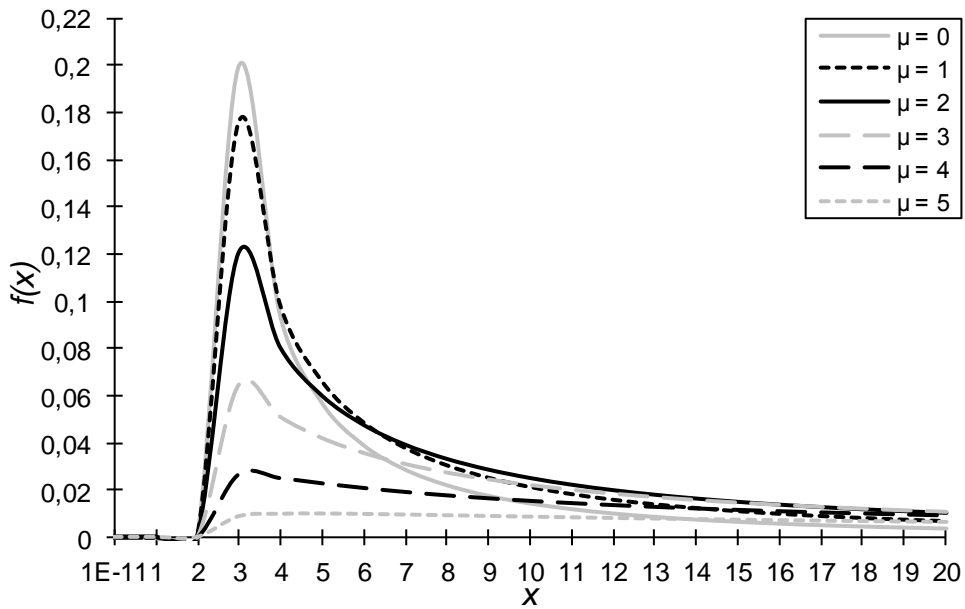
$$\begin{aligned}
 f(x; \gamma, \delta, \theta) &= \frac{\delta}{(x - \theta) \cdot \sqrt{2\pi}} \cdot \exp\left\{-\frac{1}{2}[\gamma + \delta \cdot \ln(x - \theta)]^2\right\}, & x > \theta, \\
 &= 0, & \text{else,}
 \end{aligned} \tag{53}$$

where it is valid $\mu = -\frac{\gamma}{\delta}$ and $\sigma = \frac{1}{\delta}$ between the expressions for probability density function (52) and (53).

If we substitute $\theta = 0$ (distribution minimum) into expressions for the probability density function of three-parametric lognormal distribution (52) and (53), we obtain formulas for the probability density function of two-parametric lognormal distribution.

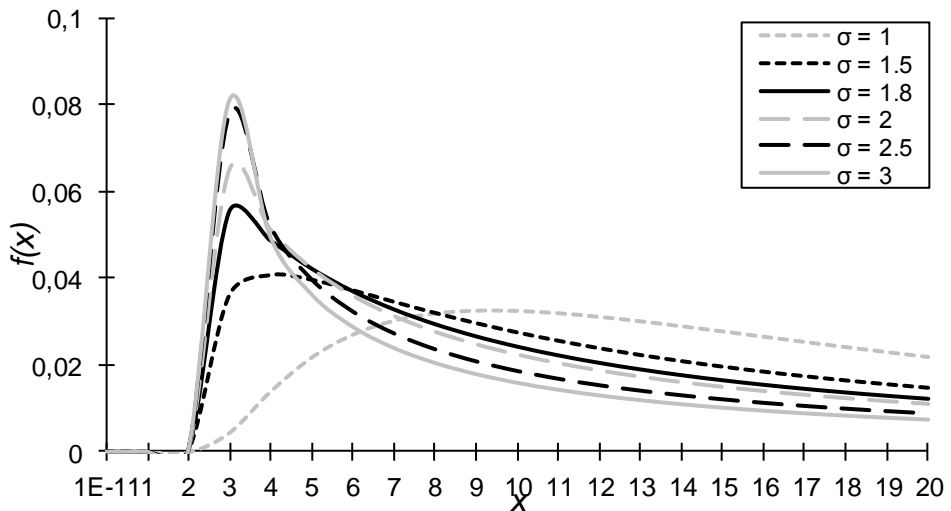
Distribution function of three-parametric lognormal distribution has the for

$$F(x) = \Phi\left[\frac{\ln(x - \theta) - \mu}{\sigma}\right], \quad x > \theta. \tag{54}$$



Source: Own research

Figure 1: Probability density function of three-parametric lognormal distribution for the values of parameters $\sigma = 2$ ($\sigma^2 = 4$); $\theta = 2$



Source: Own research

Figure 2: Probability density function of three-parametric lognormal distribution for the values of parameters $\mu = 3$; $\theta = 2$

If the random variable X has three-parametric lognormal distribution $\text{LN}(\mu, \sigma^2, \theta)$, then the random variable

$$Y = \ln(X - \theta) \quad (55)$$

has normal distribution $N(\mu, \sigma^2)$ and the random variable

$$U = \frac{\ln(X - \theta) - \mu}{\sigma} = \gamma + \delta \cdot \ln(X - \theta) \quad (56)$$

has standardized normal distribution $N(0; 1)$. Parameter μ is the expected value of random variable (55) and parameter σ^2 is the variance of this random variable. Parameter θ is the beginning of the distribution, i.e. theoretical minimum of the random variable X .

For $\omega = \exp(\sigma^2)$ the r -th common and central moments of three-parametric lognormal distribution have the form

$$\mu_r = E(X^r) = \theta + \exp\left(r \cdot \mu + \frac{r^2 \sigma^2}{2}\right), \quad (57)$$

$$\mu_r = E[(X - \mu_1)^r] = \omega^{r/2} \cdot \left[\sum_{j=0}^r (-1)^j \cdot \binom{r}{j} \cdot \omega^{(r-j) \cdot (r-j-1)/2} \right] \cdot \exp(r \cdot \mu), \quad (58)$$

specifically

$$\mu_3 = \omega^{3/2} \cdot (\omega - 1)^2 \cdot (\omega + 2) \cdot \exp(3 \cdot \mu), \quad (59)$$

$$\mu_4 = \omega^2 \cdot (\omega - 1)^2 \cdot (\omega^4 + 2\omega^3 + 3\omega^2 - 3) \cdot \exp(4 \cdot \mu). \quad (60)$$

We obtain the expressions for the expected value and variance of random variable X having three-parametric lognormal distribution from (57) and (58)

$$E(X) = \theta + \exp\left(\mu + \frac{\sigma^2}{2}\right), \quad (61)$$

$$D(X) = \exp(2\mu + \sigma^2) \cdot [\exp(\sigma^2) - 1] = \exp(2\mu) \cdot \omega \cdot (\omega - 1). \quad (62)$$

The expression for median

$$\text{Median}(X) = \theta + \exp(\mu) \quad (63)$$

comes from the expression for $100 \cdot P\%$ quantile of this distribution

$$x_P = \theta + \exp(\mu + \sigma \cdot u_P). \quad (64)$$

Three-parametric lognormal distribution is unimodal with one mode

$$\text{Mode}(X) = \theta + \exp(\mu - \sigma^2) = \theta + \frac{\exp(\mu)}{\omega}. \quad (65)$$

The relationship between the expected value, median and mode follows from the equations (61), (63) and (65)

$$E(X) > \text{Median}(X) > \text{Mode}(X), \quad (66)$$

which is typical just for positively skewed distribution.

The coefficient of variation of three-parametric lognormal distribution is a function of all three parameters μ , σ^2 and θ of this distribution

$$V(X) = \frac{\exp\left(\mu + \frac{\sigma^2}{2}\right) \sqrt{\exp(\sigma^2) - 1}}{\theta + \exp\left(\mu + \frac{\sigma^2}{2}\right)} = \frac{\exp\left(\mu + \frac{\sigma^2}{2}\right) \sqrt{\omega - 1}}{\theta + \exp\left(\mu + \frac{\sigma^2}{2}\right)}. \quad (67)$$

Gini's coefficient of three-parametric lognormal distribution depends on all three parameters μ , σ^2 and θ of this distribution, too

$$G = \frac{\exp\left(\mu + \frac{\sigma^2}{2}\right) \cdot \text{erf}\left(\frac{\sigma}{2}\right)}{\theta + \exp\left(\mu + \frac{\sigma^2}{2}\right)}. \quad (68)$$

Moment measurement of skewness and kurtosis depend on single parameter σ^2

$$\beta_1 = \sqrt{\exp(\sigma^2) - 1} \cdot [\exp(\sigma^2) + 2] = \sqrt{\omega - 1} \cdot (\omega + 2), \quad (69)$$

$$\beta_2 = [\exp(4\sigma^2) + 2\exp(3\sigma^2) + 3\exp(2\sigma^2) - 3] = (\omega^4 + 2\omega^3 + 3\omega^2 - 3). \quad (70)$$

3.2 Four-Parametric Lognormal Curves

Random variable X has four-parametric lognormal distribution with parameters μ , σ^2 , θ a τ , where $-\infty < \mu < \infty$, $\sigma^2 > 0$, $-\infty < \theta < \tau < \infty$, if its probability density function has the form

$$f(x; \mu, \sigma^2, \theta, \tau) = \frac{(\tau - \theta)}{\sigma \cdot (x - \theta) \cdot (\tau - x) \cdot \sqrt{2\pi}} \cdot \exp \left[-\frac{\left(\ln \frac{x - \theta}{\tau - x} - \mu \right)^2}{2\sigma^2} \right], \quad \theta < x < \tau, \quad (71)$$

$$= 0, \quad \text{else.}$$

Lognormal distribution with parameters μ , σ^2 , θ a τ is marked $\text{LN}(\mu, \sigma^2, \theta, \tau)$. The probability density function of four-parametric lognormal distribution can have very different shapes depending on the values of the parameters of the distribution, see Figures 3–5. Distribution may be also bimodal for $\sigma^2 > 2$ and $|\mu| < \sigma^2 \cdot \sqrt{(1 - 2/\sigma^2)} - 2 \tanh^{-1} \sqrt{(1 - 2/\sigma^2)}$. Probability density function of four-parametric lognormal distribution is often presented in the form

$$f(x; \gamma, \delta, \theta, \tau) = \frac{\delta \cdot (\tau - \theta)}{(x - \theta) \cdot (\tau - x) \cdot \sqrt{2\pi}} \cdot \exp \left[-\frac{1}{2} \left(\gamma + \delta \cdot \ln \frac{x - \theta}{\tau - x} \right)^2 \right], \quad \theta < x < \tau, \quad (72)$$

$$= 0, \quad \text{else,}$$

where it is valid between the expressions for probability density function (71) and

$$(72) \quad \mu = -\frac{\gamma}{\delta} \quad \text{and} \quad \sigma = \frac{1}{\delta}.$$

If the random variable X has four-parametric lognormal distribution $\text{LN}(\mu, \sigma^2, \theta, \tau)$, then the random variable

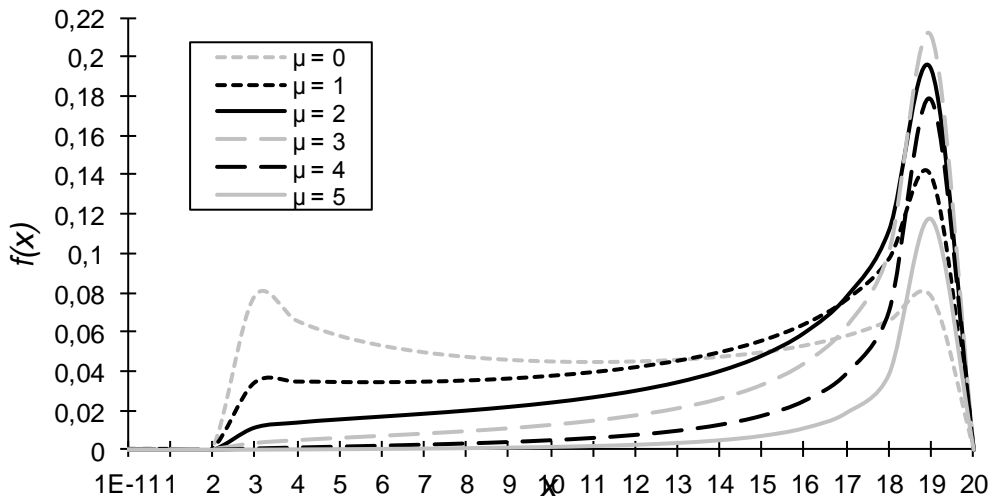
$$Y = \ln \frac{X - \theta}{\tau - X} \quad (73)$$

has normal distribution $N(\mu, \sigma^2)$ and the random variable

$$U = \frac{\ln \frac{X - \theta}{\tau - X} - \mu}{\sigma} = \gamma + \delta \cdot \ln \frac{X - \theta}{\tau - X}. \tag{74}$$

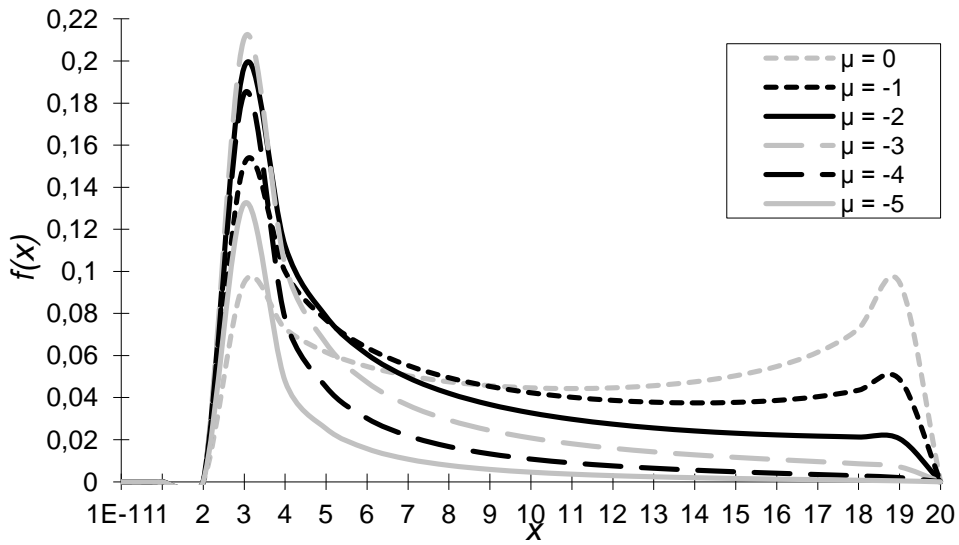
has standardized normal distribution $N(0; 1)$. Parameter μ is therefore the expected value of a random variable (73) and the parameter σ^2 is the variance of this random variable. The parameter θ is the beginning of the distribution (theoretical minimum) of a random variable X and the parameter τ represents the end point of the distribution (theoretical maximum) of the random variable X .

More on the lognormal distribution is for example in [6], [9], [10], [15] or [16].



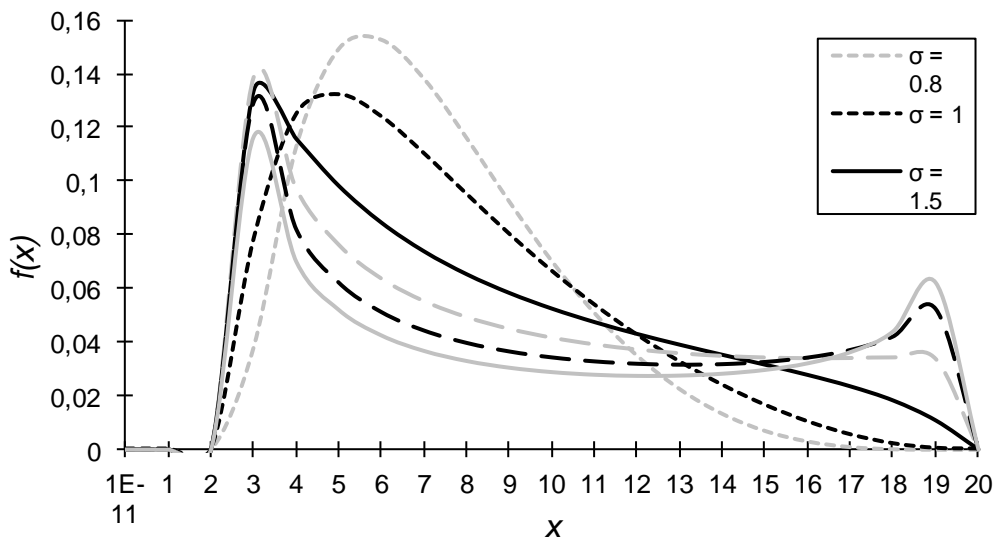
Source: Own research

Figure 3: Probability density function of four-parametric lognormal distribution for the values of parameters $\sigma = 2$ ($\sigma^2 = 4$); $\theta = 2$; $\tau = 20$



Source: Own research

Figure 4: Probability density function of four-parametric lognormal distribution for the values of parameters $\sigma = 2$ ($\sigma^2 = 4$); $\theta = 2$; $\tau = 20$



Source: Own research

Figure 5: Probability density function of four-parametric lognormal distribution for the values of parameters $\mu = -1$; $\theta = 2$; $\tau = 20$

4 Methods of Point Parameter Estimation

We focus here only on the parameter estimation of three-parametric lognormal distribution, which is the basic theoretical probability distribution of this research. Various methods of parametric estimation can be used for estimating the parameters of three-parametric lognormal distribution. There are for example the maximum likelihood method, moment method, quantile method, Kemsley's method, Cohen's method, L-moment method, TL-moment method, graphical method, etc. We focus on maximum likelihood method and on lesser-known methods of parametric estimation, i.e. Kemsley's method and Cohen's method.

4.1 Maximum Likelihood Method

Let the random sample of the sample size n comes from three-parametric lognormal distribution with probability density function (52) or (53). Then the likelihood function has the form

$$\begin{aligned}
 L(\mathbf{x}; \mu, \sigma^2, \theta) &= \prod_{i=1}^n f(x_i; \mu, \sigma^2, \theta) = \\
 &= \frac{1}{(\sigma^2)^{n/2} \cdot (2\pi)^{n/2} \cdot \prod_{i=1}^n (x_i - \theta)} \cdot \exp \left\{ \sum_{i=1}^n -\frac{[\ln(x_i - \theta) - \mu]^2}{2\sigma^2} \right\}. \tag{75}
 \end{aligned}$$

We determine the logarithm of the likelihood function

$$\begin{aligned}
 \ln L(\mathbf{x}; \mu, \sigma^2, \theta) \\
 = \sum_{i=1}^n -\frac{[\ln(x_i - \theta) - \mu]^2}{2\sigma^2} - \frac{n}{2} \cdot \ln \sigma^2 - \frac{n}{2} \cdot \ln(2\pi) - \sum_{i=1}^n \ln(x_i - \theta). \tag{76}
 \end{aligned}$$

We put in the equality to zero the first partial derivation of the logarithm of the likelihood function according to μ and according to σ^2 by

$$\frac{\partial \ln L(\mathbf{x}; \mu, \sigma^2, \theta)}{\partial \mu} = \frac{\sum_{i=1}^n [\ln(x_i - \theta) - \mu]}{\sigma^2} = 0, \quad (77)$$

$$\frac{\partial \ln L(\mathbf{x}; \mu, \sigma^2, \theta)}{\partial \sigma^2} = \frac{\sum_{i=1}^n [\ln(x_i - \theta) - \mu]^2}{2\sigma^4} - \frac{n}{2\sigma^2} = 0. \quad (78)$$

We obtain maximum likelihood estimations of the parameters μ and σ^2 for the given parameter θ after treatment

$$\hat{\mu}(\theta) = \frac{\sum_{i=1}^n \ln(x_i - \theta)}{n}, \quad (79)$$

$$\hat{\sigma}^2(\theta) = \frac{\sum_{i=1}^n [\ln(x_i - \theta) - \hat{\mu}(\theta)]^2}{n}. \quad (80)$$

If the value of the parameter θ is known, we get the maximum likelihood estimations of the remaining two parameters of three-parametric lognormal distribution using the expressions (79) and (80). However, if the value of the parameter θ is unknown, the problem is more complicated. It can be proved that if the parameter θ closes to $\min\{X_1, X_2, \dots, X_n\}$, then the maximum likelihood approaches to infinity. The maximum likelihood method is also often combined with Cohen's method, where we put the smallest sample value to be equal to the $100 \cdot (n+1)^{-1}$ -percentage quantile

$$x_{\min}^V = \hat{\theta} + \exp(\hat{\mu} + \hat{\sigma} \cdot u_{(n+1)^{-1}}). \quad (81)$$

Equation (81) is then combined with a system of equations (79) and (80).

For solving of maximum likelihood equations (79) and (80) it is also possible to use $\hat{\theta}$ satisfying the equation

$$\sum_{i=1}^n (x_i - \hat{\theta}) + \frac{\sum_{i=1}^n \frac{z_i}{(x_i - \hat{\theta})}}{\hat{\sigma}(\hat{\theta})} = 0, \quad (82)$$

where

$$z_i = \frac{\ln(x_i - \hat{\theta}) - \hat{\mu}(\hat{\theta})}{\hat{\sigma}(\hat{\theta})}, \quad (83)$$

where $\hat{\mu}(\hat{\theta})$ and $\hat{\sigma}(\hat{\theta})$ satisfy equations (79) and (80) with the parameter θ replaced by $\hat{\theta}$. We may also obtain the limits of variances

$$n \cdot D(\hat{\theta}) = \frac{\sigma^2 \cdot \exp(2\mu)}{\omega \cdot [\omega \cdot (1 + \sigma^2) - 2\sigma^2 - 1]}, \quad (84)$$

$$n \cdot D(\hat{\mu}) = \frac{\sigma^2 \cdot [\omega \cdot (1 + \sigma^2) - 2\sigma^2]}{\omega \cdot (1 + \sigma^2) - 2\sigma^2 - 1}, \quad (85)$$

$$n \cdot D(\hat{\sigma}) = \frac{\sigma^2 \cdot [\omega \cdot (1 + \sigma^2) - 1]}{\omega \cdot (1 + \sigma^2) - 2\sigma^2 - 1}. \quad (86)$$

Especially difficulties related with the use of the equations (79), (80) and (82) lead us to think about other methods.

4.2 Kemsley's Method

Kemsley used the estimation method, which is a combination of moment and quantile methods of parametric estimation. This method of parametric estimation put into equality the sample quantiles $x_{p_1}^V$ and $x_{1-p_1}^V$ and the corresponding theoretical quantiles of the probability distribution. We get the last equation so that we put sample average equal to the expected value of the probability distribution ("K" means Kemsley's estimation)

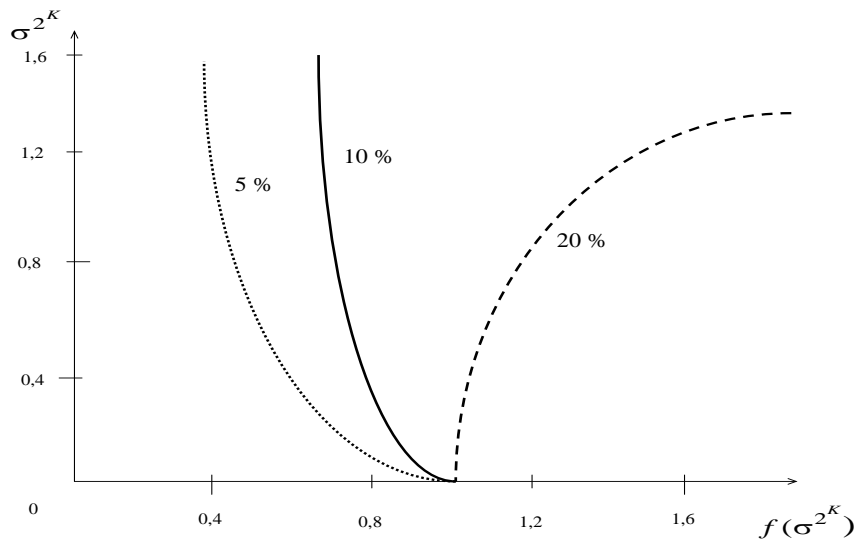
$$x_{p_1}^V = \theta^K + \exp(\mu^K + \sigma^K \cdot u_{p_1}), \quad (87)$$

$$\bar{x} = \theta^K + \exp\left(\mu^K + \frac{\sigma^{2K}}{2}\right), \quad (88)$$

$$x_{1-p_1}^V = \theta^K + \exp(\mu^K - \sigma^K \cdot u_{p_1}). \quad (89)$$

Now we solve a similar system of equations as in the case of quantile method of parameter estimation and

$$f(\sigma^{2K}) = \frac{\exp\left(\frac{\sigma^{2K}}{2}\right) - \exp(\sigma^K \cdot u_{p_1})}{\exp(-\sigma^K \cdot u_{p_1}) - \exp\left(\frac{\sigma^{2K}}{2}\right)} = \frac{\bar{x} - x_{p_1}^V}{x_{(1-p_1)}^V - \bar{x}}. \quad (90)$$



Source: Own research

Figure 6: Graph σ^{2K} for Kemsley's method of parametric estimation for $p_1 = 0,05; 0,10$ and $0,20$

The proposal for the solution of equation (90) σ^{2K} determines approximately using Figure 6. Then we obtain the values of the remaining two parameters using the expressions

$$\mu^K = \ln(x_{P_1}^V - \bar{x}) - \ln \left[\exp(\sigma^K \cdot u_{P_1}) - \exp\left(\frac{\sigma^{2K}}{2}\right) \right], \quad (91)$$

$$\theta^K = x_{P_1}^V - \exp(\mu^K + \sigma^K \cdot u_{P_1}). \quad (92)$$

4.3 Cohen's Method of the Smallest Sample Value

It is known that parameter θ determines the beginning of three-parametric lognormal distribution. In this case, an appropriate estimation would be a function of the smallest sample value. This method constitutes an alternative to the method of maximum likelihood. This keeps the equations (79) and (80) and needed the third equation is based on the smallest sample value x_{\min} . If the value x_{\min} is contained n_{\min} -times in the sample, then the sample quantile of order $\frac{n_{\min}}{n}$ in the third equation is putted into equality to the corresponding theoretical quantile of the distribution. Thus, Cohen's method represents a combination of maximum likelihood method and the quantile method. We can get the parameter estimations obtained by Cohen's method with the system of equations ("C" means Cohen's estimation)

$$\mu^C = \frac{\sum_{i=1}^n \ln(x_i - \theta^C)}{n}, \quad (93)$$

$$\sigma^{2C} = \frac{\sum_{i=1}^n [\ln(x_i - \theta^C) - \mu^C]^2}{n}, \quad (94)$$

$$\theta^C = x_{n_{\min}/n}^V - \exp(\mu^C + \sigma^C \cdot u_{n_{\min}/n}). \quad (95)$$

5 Appropriateness of the Model

It is also necessary to assess the suitability of constructed model or choose a model from several alternatives, which is made by some criterion, which can be a sum of absolute deviations of the observed and theoretical frequencies for all intervals

$$S = \sum_{i=1}^k |n_i - n \pi_i| \quad (96)$$

or known criterion χ^2

$$\chi^2 = \sum_{i=1}^k \frac{(n_i - n \pi_i)^2}{n \pi_i}, \quad (97)$$

where n_i are the observed frequencies in individual intervals, π_i are the theoretical probabilities of membership of statistical unit into the i -th interval, n is the total sample size of corresponding statistical file, $n \cdot \pi_i$ are the theoretical frequencies in individual intervals, $i = 1, 2, \dots, k$, and k is the number of intervals.

The question of the appropriateness of the given curve for model of the distribution of wage is not entirely conventional mathematical-statistical problem in which we test the null hypothesis

H_0 : The sample comes from the supposed theoretical distribution
against the alternative hypothesis

$$H_1: \text{non } H_0,$$

because in goodness of fit tests in the case of wage distribution we meet frequently with the fact that we work with large sample sizes and therefore the tests would almost always lead to the rejection of the null hypothesis. This results not only from the fact that with such large sample sizes the power of the test is so high at the chosen significance level that the test uncovers all the slightest deviations of the actual wage distribution and a model, but it also results from the principle of construction of the test. But practically we are not interested in such small deviations, so only gross agreement of the model with reality is sufficient and we

so called “borrow” the model (curve). Test criterion χ^2 can be used in that direction only tentatively. When evaluating the suitability of the model we proceed to a large extent subjective and we rely on experience and logical analysis.

6 Database

The data base of the research consists in employees of the Czech Republic. There are a total set of all employees of the Czech Republic together and further the partial sets broken down by various demographic and socio-economic factors. Figures 7 and 8 provide information on the geographic position of the Czech Republic in Europe and look at the map of the Czech Republic. The researched variable is the gross monthly wage in CZK (nominal wage). Data come from the official website of the Czech Statistical Office. The data was in the form of interval frequency distribution, since the individual data is not currently available.



Source: www.obrazky.cz

Figure 7: Position of the Czech Republic in Europe

Researched period represents years 2003–2010. Employees of the Czech Republic were classified according to gender, job classification (CZ-ISCO), the classification of economic activities, age and educational attainment. Branch Classification of Economic Activities (OKEC) has been replaced by Classification of Economic Activities (CZ-NACE) during researched period. This fact therefore disrupts the continuity of the obtained time series during the analysis period.



Source: www.obrazky.cz

Figure 8: Map of the Czech Republic

The main classes of Job Classification CZ-ISCO form: Managers (code 1000); Professionals (code 2000); Technicians and Associate Professionals (code 3000); Clerical Support Workers (code 4000); Service and Sales Workers (code 5000); Skilled Agricultural, Forestry and Fishery

Workers (code 6000); Craft and Related Trades Workers (code 7000); Plant and Machine Operators, and Assemblers (code 8000); Elementary Occupations (code 9000).

The main classes of Branch Classification of Economic Activities – OKEC (years 2003-2008) are: A-B – Agriculture, Fishing; C-E – Industry; F – Construction; G – Trade, Repairs; H – Hotels and Restaurants; I – Transport, Storage; J – Financial intermediation; K – Real Estate, Renting; L – Public Administration; M – Education; N – health; O – Other Services.

The main classes of Classification of Economic Activities – CZ-NACE (years 2009-2010) represent: A – Agriculture, Forestry and Fishing; B-E – Industry; F – Construction; G – Wholesale and Retail Trade, Repair of Motor Vehicles and Motorcycles; H – Transportation and Storage; I – Accommodation and Food Service Activities; J – Information and Communication; K – Financial

and Insurance Activities; L – Real Estate activities; M – Professional, Scientific and Technical Activities; N – Administrative and Support Service Activities; O – Public Administration and Defense, Compulsory Social Security; P – Education; Q – Human Health and Social Work Activities; R – Arts, Entertainment and Recreation; S – Other Service Activities.

Classification by age include the following age intervals: to 19 years; from 20 to 24 years; from 25 to 29 years; from 30 to 34 years; from 35 to 39 years; from 40 to 44 years; from 45 to 49 years; from 50 to 54 years; from 55 to 59 years; from 60 to 64 years; from 65 years.

Classification according to educational attainment distinguishes the following five levels of educational attainment of the employee: Primary education; Apprenticeship; Secondary with GCE; Higher post-secondary schools; University. Tables 4–9 provide information on the sample sizes of sample sets of employees of single researched wage distribution.

Table 4: Sample sizes of wage distribution by gender

Gender	Year							
	2003	2004	2005	2006	2007	2008	2009	2010
Total	1,018,934	1,404,496	1,515,527	1,614,372	1,673,498	1,711,811	1,651,506	1,662,829
Men	559,863	711,551	769,802	813,821	858,656	875,139	846,028	850,788
Women	459,071	692,945	745,725	800,551	814,842	836,672	805,478	812,041

Source: www.czso.cz

Table 5: Sample sizes of wage distribution by Job Classification CZ-ISCO

CZ-ISCO code	Year							
	2003	2004	2005	2006	2007	2008	2009	2010
1000	60,300	84,264	91,302	96,382	104,516	107,599	109,281	110,155
2000	109,779	241,959	248,320	270,252	273,497	285,880	289,894	295,775
3000	250,639	355,319	383,730	402,651	402,553	413,067	399,798	401,402

4000	77,565	95,552	101,920	111,470	118,124	122,083	123,784	125,778
5000	63,685	95,247	108,172	122,661	128,053	134,127	134,560	134,370
6000	9,912	10,697	11,417	10,098	8,859	7,877	7,630	7,250
7000	193,715	211,356	226,527	232,399	243,246	243,390	221,308	225,420
8000	192,378	214,229	240,057	258,177	282,001	284,634	260,355	256,472
9000	60,961	95,873	104,082	110,282	112,649	113,154	104,896	106,207

Source: www.czso.cz

Table 6: Sample sizes of wage distribution by Branch Classification of Economic Activities OKEČ

OKEČ	Year							
	2003	2004	2005	2006	2007	2008	2009	2010
A+B	28,132	31,055	33,004	27,502	24,296	21,537	–	–
C-E	431,534	479,817	522,097	554,783	600,924	603,951	–	–
F	38,261	42,223	45,242	43,941	50,073	50,437	–	–
G	52,070	63,221	74,232	93,353	111,944	120,464	–	–
H	8,556	11,188	12,020	15,447	16,858	16,997	–	–
I	161,895	157,881	142,185	141,819	143,612	144,536	–	–
J	47,932	52,140	48,601	51,893	53,506	55,993	–	–
K	35,911	43,758	49,080	59,836	67,604	79,003	–	–
L	68,971	192,993	217,590	235,536	232,800	233,438	–	–
M	33,508	173,477	183,277	189,068	187,325	188,730	–	–
N	93,480	125,784	149,429	160,700	144,471	155,533	–	–
O	18,684	30,959	38,770	40,494	40,085	41,192	–	–

Source: www.czso.cz

Table 7: Sample sizes of wage distribution by Classification of Economic Activities CZ-NACE

CZ-NACE	Year							
	2003	2004	2005	2006	2007	2008	2009	2010
A	–	–	–	–	–	–	20,560	18,659
B-E	–	–	–	–	–	–	558,904	560,299

F	-	-	-	-	-	-	50,789	52,769
G	-	-	-	-	-	-	125,373	130,348
H	-	-	-	-	-	-	147,328	141,193
I	-	-	-	-	-	-	17,132	16,673
J	-	-	-	-	-	-	42,058	43,602
K	-	-	-	-	-	-	57,149	57,715
L	-	-	-	-	-	-	5,540	5,093
M	-	-	-	-	-	-	20,922	22,978
N	-	-	-	-	-	-	41,588	44,533
O	-	-	-	-	-	-	208,606	212,765
P	-	-	-	-	-	-	185,453	186,092
Q	-	-	-	-	-	-	143,595	143,877
R	-	-	-	-	-	-	23,756	23,033
S	-	-	-	-	-	-	2,753	3,200

Source: www.czso.cz

Table 8: Sample sizes of wage distribution by age

Age (in years)	Year							
	2003	2004	2005	2006	2007	2008	2009	2010
- 19	2,805	3,567	4,314	5,887	6,879	6,455	4,245	3,927
20 - 24	63,496	76,595	86,317	97,025	105,523	106,958	94,097	91,160
25 - 29	129,298	166,682	178,259	188,289	193,222	190,866	177,961	177,044
30 - 34	121,054	173,799	197,020	217,720	227,325	231,284	220,500	216,899
35 - 39	122,324	170,268	183,513	198,609	210,780	226,740	233,095	246,619
40 - 44	123,278	184,904	204,368	218,373	225,528	226,265	216,461	218,695
45 - 49	148,936	198,188	205,107	208,653	209,454	217,468	220,087	227,237
50 - 54	166,456	221,988	222,759	220,744	220,894	216,944	201,687	194,387
55 - 59	113,813	163,222	182,059	194,592	200,682	207,352	201,606	203,674
60 - 64	22,019	36,571	42,151	52,473	60,501	66,795	66,452	68,220
65 +	5,455	8,712	9,660	12,007	12,710	14,684	15,315	14,967

Source: www.czso.cz

Table 9: Sample sizes of wage distribution by educational attainment

Education	Year							
	2003	2004	2005	2006	2007	2008	2009	2010
Primary education	95,112	119,480	125,972	129,027	135,399	137,190	120,254	116,383
Apprenticeship	377,347	470,688	523,744	553,522	587,081	591,669	557,780	555,266
Secondary with GCE	408,562	560,237	575,668	621,306	629,447	644,576	625,631	627,073
Higher post-secondary schools	15,749	29,144	40,055	42,856	47,967	54,439	57,747	64,684
University	122,164	224,947	250,088	267,661	273,604	283,937	290,094	299,423

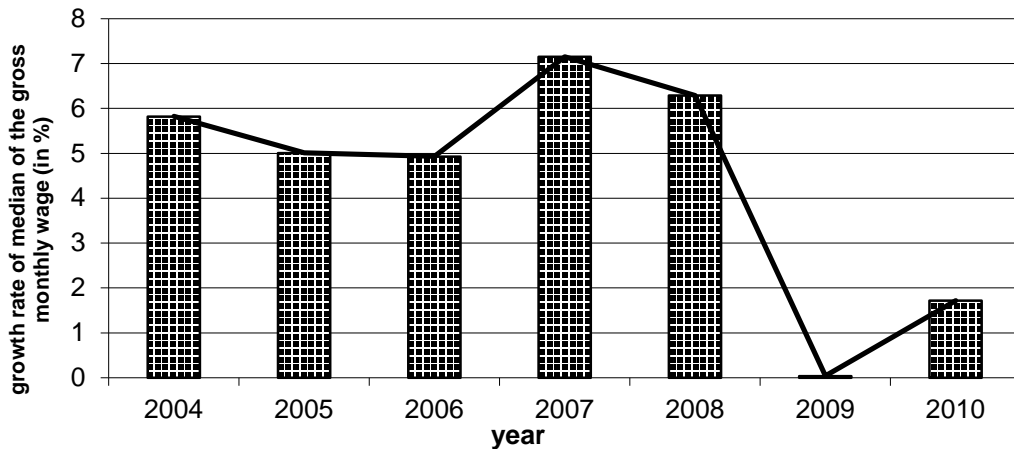
Source: www.czso.cz

7 Main Results

All calculations were made using the statistical program packages Statgraphics and SAS, spreadsheet Microsoft Excel and mathematical program R.

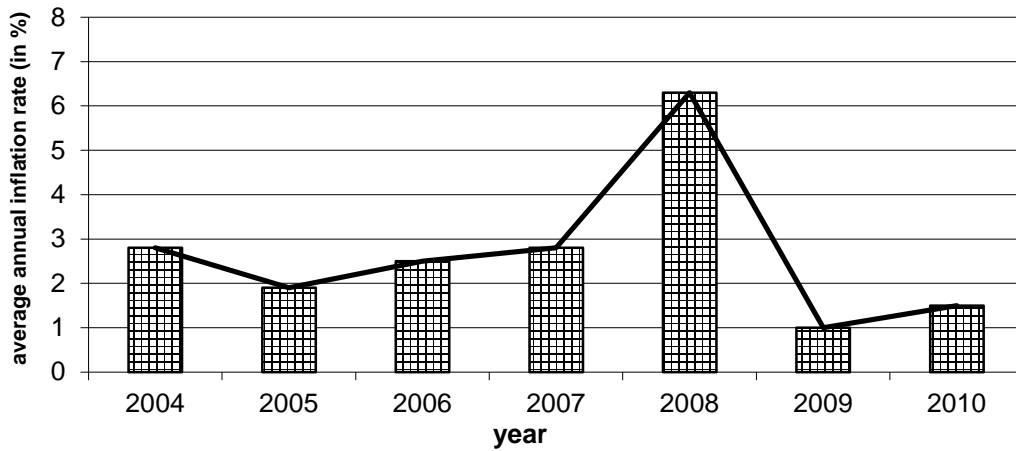
Figures 9 and 10 provide an overview of the development of the annual growth rate of the level of gross monthly wage in the Czech Republic in the period and the overview of the development of the average annual inflation. Because the growth rate is calculated from the growth coefficient, which is the ratio of two consecutive values of the time series, we would have data for 2002 to calculate the growth rate for the year 2003. Since 2002 is not included in the analysis period, the growth rate for 2003 is not presented here. The impact of the global economic crisis on the development of the wage level in the Czech Republic and on the development of inflation is clearly evident from these figures. It is apparent from Figure 9 that the annual growth rate of middle gross monthly wage in the Czech Republic dropped to almost zero in 2009. It has increased slightly over the next year, but it is far below the values before crisis. It is plainly evident from Figure 10 that the average annual inflation rate fell sharply in 2009, but it again slightly increase during the next year, too.

Figure 11 presents the dependence of the value of criterion (96) on the sample size. A similar situation exists in term of the criterion (97). This is the wage distribution broken down by classification of economic activities CZ-NACE, i.e. a total of 32 wage distributions of the years 2009–2010. This is only a chosen file of wage distribution for clear visibility, since we obtain similar results also in terms of all surveyed wage distribution. The linear dependence of the value of criterion S on the sample size follows from Figure 11. Figure 12 presents the results of significance tests for the linear dependence. We can see from Figure 12 that both significance tests of regression coefficient are significant at 5%, but even at 1% significance level (t-test and F-test of regression coefficient provide equivalent results form the linear dependence between two variables). Linear dependence of the value of criterion S on sample size is therefore proved even at 1% significance level.



Source: Own research

Figure 9: Annual growth rate of the median of gross monthly wage in the Czech Republic in 2003–2010 (in %)

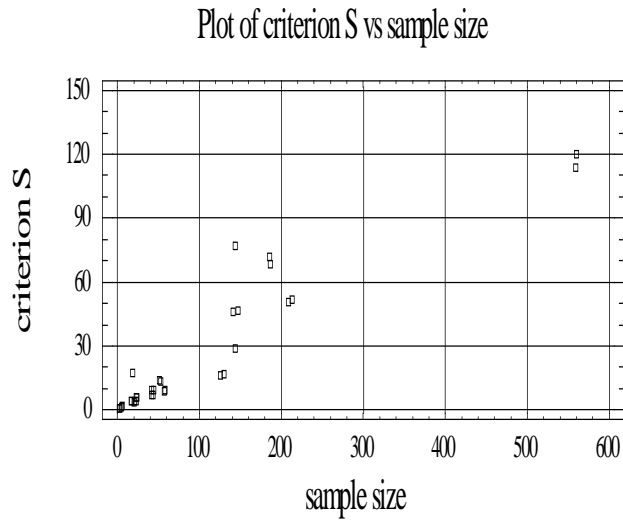


Source: Own research

Figure 10: Average annual inflation rate in 2003–2010 (in %)

The determination coefficient in Figure 12 says that 86.57 % of the variability of criterion S in given 32 wage distributions can be explained by the chosen regression line. The correlation coefficient in Figure 12 shows a very tight direct linear dependence of the criterion S on sample size of wage distribution.

Table 10 presents parameter estimations obtained using the various three methods of point parameter estimation and the value of criterion S for the total wage distribution of the Czech Republic. This table describes approximately the research results of all 328 wage distribution. We obtained in total research that the method of TL-moments provided the most accurate results in almost all cases of wage distribution with minor exceptions, deviations occur mainly at both ends of the wage distribution due to the extreme open intervals of interval frequency distribution. In the results of Table 10 for total sets of wage distribution of the Czech Republic in 2003–2010 method of TL-moments always brings the most accurate results in terms of criterion S .



Source: Own research

Figure 11: Dependence of the value of criterion S (in 1,000) on sample size
(in 1,000) - broken down by educational attainment, years 2003–2010

In terms of research of all 328 wage distribution, method of L-moments brought the second most accurate results in more than in half of the cases. Deviations occur again especially at both ends of the distribution. In the results of Table 10 method of L-moments brought the second most accurate results in terms of all total sets of wage distribution of the Czech Republic in 2003–2010.

Regression Analysis - Linear model: $Y = a + b \cdot X$

 Dependent variable: criterion S
 Independent variable: sample size

Parameter	Estimate	Standard Error	T Statistic	P-Value
Intercept	3,20675	2,71914	1,17933	0,2475
Slope	0,222708	0,0160139	13,9071	0,0000

 Analysis of Variance

Source	Sum of Squares	Df	Mean Square	F-Ratio	P-Value
Model	28734,2	1	28734,2	193,41	0,0000
Residual	4457,03	30	148,568		
Total (Corr.)	33191,2	31			

Correlation Coefficient = 0,930439
 R-squared = 86,5717 percent
 Standard Error of Est. = 12,1888

Source: Own research

Figure 12: Dependence of the value of criterion S (in 1,000) on sample size
 (in 1,000)-broken down by educational attainment, years 2003–2010³⁾

³⁾ Output of the statistical program Statgraphics; decimal comma is used instead decimal point in this output

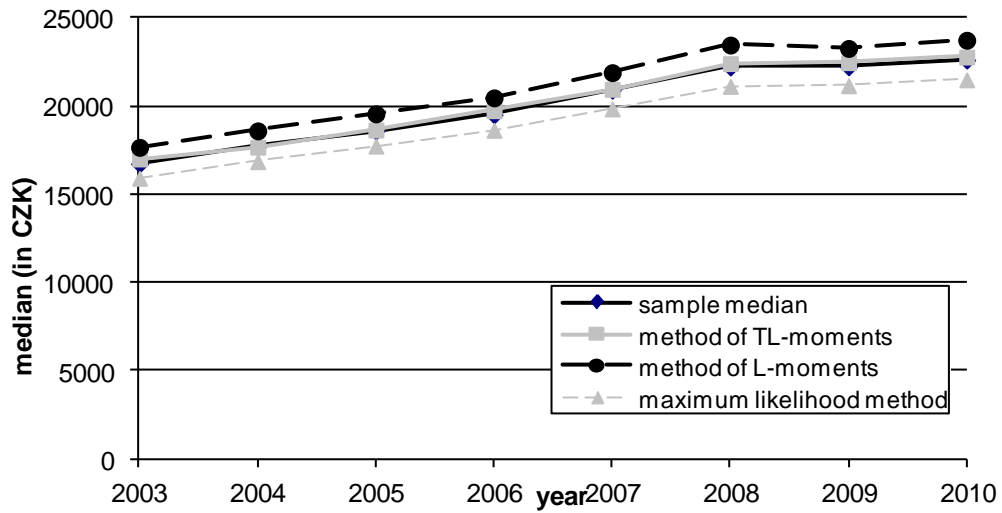
Table 10: Parameter estimations obtained using the various three methods of point parameter estimation and the value of criterion S for the total wage distribution of the Czech Republic

Year	Method								
	Method of TL-moments			Method of L-moments			Maximum likelihood method in combination with Cohen's method		
	Parameter estimation			Parameter estimation			Parameter estimation		
	μ	σ^2	θ	μ	σ^2	θ	μ	σ^2	θ
2003	9.059 747	0.630 754	9,065.52	9.017 534	0.608 369	7,664.46	9.741 305	0.197 395	2.07
2004	9.215 324	0.581 251	8,552.10	9.241 235	0.507 676	6,541.16	9.780 008	0.232 406	0.22
2005	9.277 248	0.573 002	8,872.54	9.283 399	0.515 290	6,977.45	9.833 604	0.228 654	0.27
2006	9.313 803	0.577 726	9,382.66	9.283 883	0.543 225	7,868.21	9.890 594	0.210 672	0.59
2007	9.382 135	0.680 571	10,027.84	9.387 739	0.601 135	7,902.64	9.950 263	0.268 224	0.16
2008	9.438 936	0.688 668	10,898.39	9.423 053	0.624 340	8,754.64	10.017 433	0.264 124	0.19
2009	9.444 217	0.703 536	10,640.53	9.431 478	0.631 013	8,684.51	10.019 787	0.269 047	0.20
2010	9.482 060	0.681 258	10,616.80	9.453 027	0.621 057	8,746.20	10.033 810	0.269 895	0.20

	Criterion S	Criterion S	Criterion S
2003	108,437.01	133,320.79	248,331.74
2004	146,509.34	248,438.78	281,541.41
2005	137,422.05	231,978.79	311,008.23
2006	149,144.68	216,373.24	325,055.67

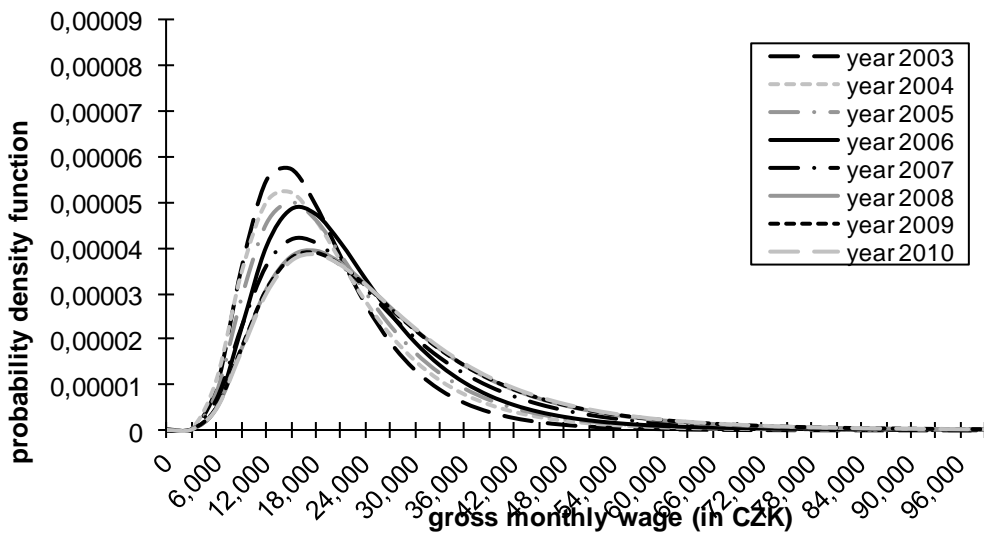
2007	198,670.74	366,202.87	370,373.62
2008	206,698.93	357,668.48	391,346.02
2009	193,559.55	335,999.20	359,736.37
2010	200,060.20	339,871.80	378,629.15

Source: Own research



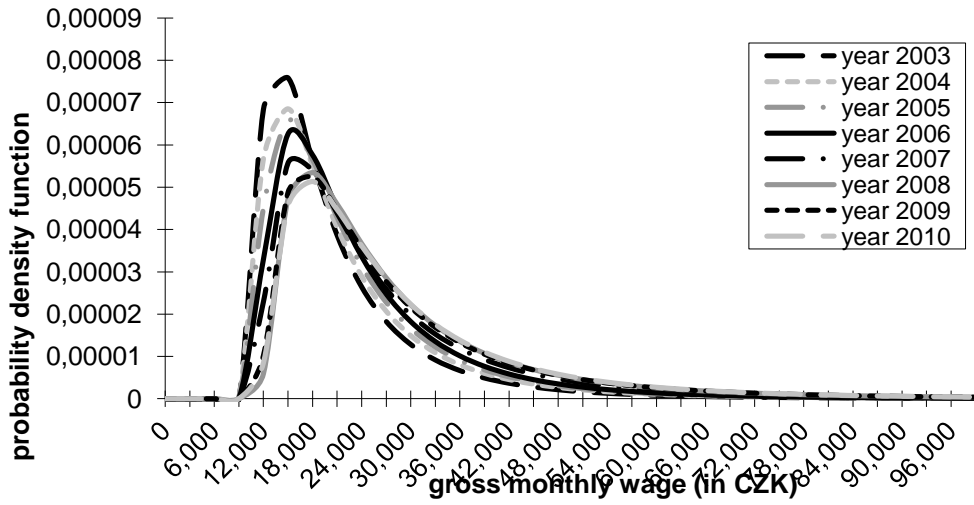
Source: Own research

Figure 13: Development of sample and theoretical median of three-parametric lognormal curves with parameters estimated using three various methods of parameter estimation



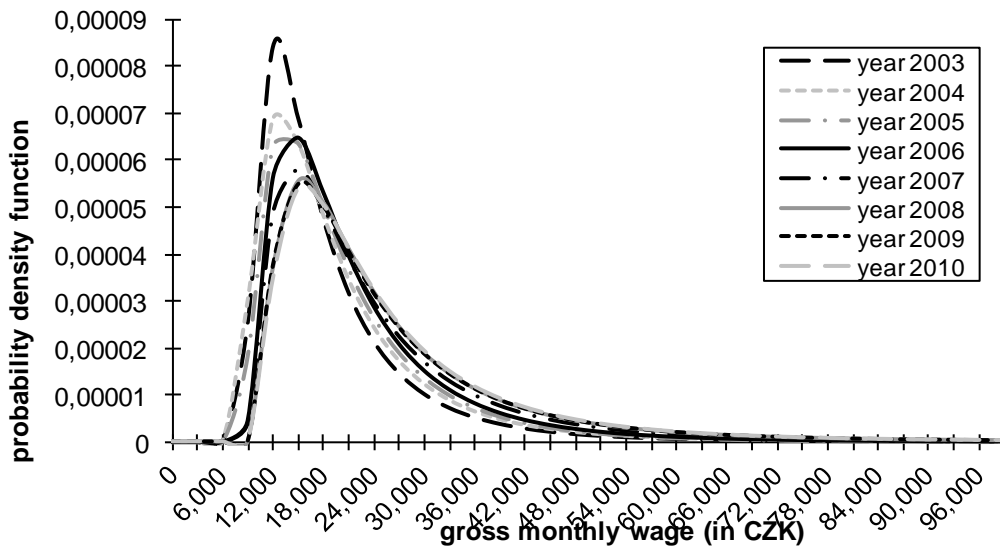
Source: Own research

Figure 14: Development of probability density function of three-parametric lognormal curves with parameters estimated using the method of TL-moments



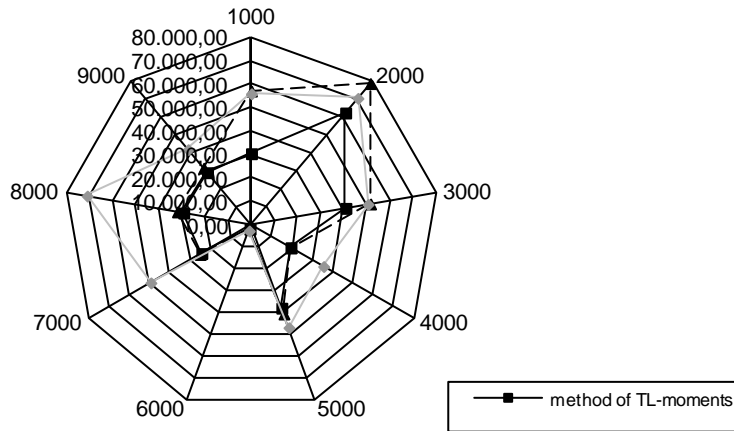
Source: Own research

Figure 15: Development of probability density function of three-parametric lognormal curves with parameters estimated using the method of L-moments



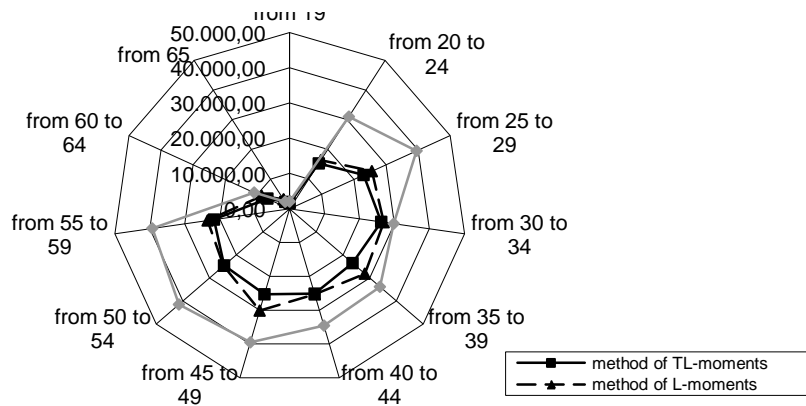
Source: Own research

Figure 16: Development of probability density function of three-parametric lognormal curves with parameters estimated using the maximum likelihood method



Source: Own research

Figure 17: The values of S criterion for model three-parametric lognormal curves with parameters estimated by methods of point parameter estimation (year 2010, broken down by codes of job classification)



Source: Own research

Figure 18: The values of S criterion for model three-parametric lognormal curves with parameters estimated by methods of point parameter estimation (year 2010, broken down by age intervals in years)

Overall, maximum likelihood method was the third in most cases in terms of accuracy of the results obtained (in all cases in Table 10). Figure 13 also gives some idea of the accuracy of the researched methods of point parameter estimation. This figure shows the development of the sample median of gross monthly wage for the total set of all employees of the Czech Republic together in the period 2003–2010 and the development of corresponding theoretical median of model three-parametric lognormal curves with parameters estimated by three various methods of point parameter estimation. We can observe from this figure that the curve characterizing the course of theoretical median of three-parametric lognormal distribution with parameters estimated using the method of TL-moments adheres the most to the curve showing the development of the sample median. The other two curves articulating the development of the theoretical median of three-parametric lognormal curves with parameters estimated by method of L-moments and by maximum likelihood method are relatively remote from the course of sample median of wage distribution.

Figures 14–16 represents the development of probability density function of three-parametric lognormal curves with parameters estimated using the method of TL-moments, method of L-moments and maximum likelihood method. This is again a development of model distributions of the total wage distribution of the Czech Republic for all employees of the Czech Republic together in the period 2003—2010. We can see that the shapes of the lognormal curves with parameters estimated using the method of L-moments and maximum likelihood method (Figures 15 and 16) are similar mutually and they are very different from the shape of three-parametric lognormal curves with parameters estimated by the method of TL-moments (Figure 14).

Figure 17 shows the values of criterion S of wage distributions broken down by job classification in 2010 and Figure 18 presents the same of wage distributions broken down by five-year age intervals in 2010. High accuracy of the method of TL-moments against the other two methods of point parameter estimation is

evident from these two figures, too.

Other methods usable for processing of the economic data are presented for example in [18]–[20].

8 Conclusion

Alternative category of moment characteristics of probability distributions was introduced here. There are the characteristics in the form of L-moments and TL-moments. Accuracy of the methods of L-moments and TL-moments was compared with the accuracy of the maximum likelihood method using such criterion as the sum of all absolute deviations of the observed and theoretical frequencies for all intervals. Higher accuracy of the method of TL-moments due to the method of L-moments and to the maximum likelihood method was proved by studying of the set of 328 wage distribution. However, the advantages of the method of L-moments to the maximum likelihood method were demonstrated here, too. The values of χ^2 criterion were also calculated for each wage distribution, but this test led always to the rejection of the null hypothesis about the supposed shape of the distribution due to the large sample sizes, which are typical for wage distribution. The dependence the value of criterion χ^2 and the value of criterion of the sum of all absolute deviations of observed and theoretical frequencies on the sample size follows from the construction of the test. The linear dependence of the value of criterion of the sum of all absolute deviations of observed and theoretical frequencies on the sample size was proved even at 1% significance level.

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