Theoretical Mathematics & Applications, vol.6, no.2, 2016, 77-87 ISSN: 1792-9687 (print), 1792-9709 (online) Scienpress Ltd, 2016

Packing dimension for β -shifts

Zheng Yin¹ and Xiucheng Hong²

Abstract

This article is devoted to the study of the packing entropy for maps with g-almost product property, a weak form of specification property. In particular, our result can be applied to the packing dimension for β -shifts.

Mathematics Subject Classification: 37C45

Keywords: Packing entropy; Packing dimension; β -shifts

1 Introduction

(X, d, T) (or (X, T) for short) is a topological dynamical system which means that (X, d) is a compact metric space together with a continuous selfmap $T : X \to X$. Denote by M(X), M(X, T) and E(X, T) the sets of all Borel probability measures, *T*-invariant Borel probability measures, and ergodic measures on *X*, respectively. It is well known that M(X) and M(X, T)equipped with weak^{*} topology are both convex, compact spaces.

¹ School of Mathematical Sciences, Nanjing Normal University, Nanjing 210023, Jiangsu, P.R.China. E-mail: zhengyinmail@126.com

² School of Mathematical Sciences, Nanjing Normal University, Nanjing 210023, Jiangsu, P.R.China. E-mail: 736712809@qq.com

Article Info: *Received*: October 20, 2015. *Revised*: December 3, 2015. *Published online*: April 5, 2016.

For an *T*-invariant subset $Z \subset X$, let M(Z, T) denote the subset of M(X, T)for which the measures μ satisfy $\mu(Z) = 1$ and E(Z, f) denote those which are ergodic. For a positive integer n, define the n-th empirical measure $\mathcal{E}_n : X \to M(X)$ by

$$\mathcal{E}_n(x) = \frac{1}{n} \sum_{k=0}^{n-1} \delta_{T^k x},$$

where δ_x denotes the Dirac measure at x. Let $A(x_n)$ be the set of all limit points of sequence $\{x_n\}$.

This investigation uses the framework introduced and developed by Olsen [3, 4, 5, 6] and Olsen and Winter [7]. Consider the continuous and affine deformations of \mathcal{E}_n i.e. pairs (Y, Ξ) where Y is a vector space with linear compatible metric and $\Xi : M(X) \to Y$ is a continuous and affine map. Let

$$\Delta_{equ}(C) = \{ x \in X | A(\Xi \mathcal{E}_n(x)) = C \}$$

and

$$\Delta_{sup}(C) = \{ x \in X | A(\Xi \mathcal{E}_n(x)) \subset C \}.$$

where C is a convex and closed subset of $\Xi(M(X,T))$.

There are some interesting results about the description of the structure (Hausdorff dimension or topological entropy or topological pressure) of $\Delta_{equ}(C)$ and $\Delta_{sup}(C)$. Recently, Zhou, Chen and Cheng [10] studied the packing entropy of $\Delta_{equ}(C)$ and $\Delta_{sup}(C)$ for maps with specification property. Pfister and Sullivan [8] obtained the Bowen entropy in a dynamical system with the g-almost product property which is weaker than specification. Zhou and Chen [9] gave topological pressure for maps with g-almost product property.

Motivated by the work of Zhou, Chen and Cheng (see [9, 10]), we study the packing entropy in a dynamical system with the g-almost product property. In particular, our result can be applied to the packing dimension for β -shifts.

2 Definitions and main result

Let (X,T) be a topological dynamical system and C(X) the space of continuous functions from X to \mathbb{R} . For $\mu, \nu \in M(X)$, define a compatible metric d on M(X) as follows:

$$d(\mu,\nu) := \sum_{i\geq 1} 2^{-i} \left| \int f_i d\mu - \int f_i d\nu \right|$$

where $\{f_i\}_{i=1}^{\infty}$ is the subset of C(X) with $0 \leq f_i(x) \leq 1, i = 1, 2, \cdots$. It is convenient to use an equivalent metric on X, still denoted by $d, d(x, y) := d(\delta_x, \delta_y)$.

For every $\epsilon > 0$, denote by $B_n(x, \epsilon)$, $\overline{B}_n(x, \epsilon)$ the open and closed balls of radius $\epsilon > 0$ in the metric d_n around x respectively, i.e.,

$$B_n(x,\epsilon) = \{y \in X : d_n(x,y) < \epsilon\}, \overline{B}_n(x,\epsilon) = \{y \in X : d_n(x,y) \le \epsilon\}.$$

Where $n \in \mathbb{N}$, the *n*-th Bowen metric d_n on X is defined by

$$d_n(x,y) = \max \left\{ d(T^k x, T^k y) : k = 0, 1, \cdots, n-1 \right\}.$$

2.1 Continuous affine deformation Ξ .

Definition 2.1. [1] If Y is a vector space and d' is a metric in Y, then d' is linearly compatible if

- (1) For all $x_1, x_2, y_1, y_2 \in Y, d'(x_1 + x_2, y_1 + y_2) \le d'(x_1, y_1) + d'(x_2, y_2);$
- (2) For all $x, y \in Y$ and all $\lambda \in \mathbb{R}, d'(\lambda x, \lambda y) \leq |\lambda| d'(x, y)$.

2.2 Packing entropy

Given $Z \subset X, \epsilon > 0$ and $N \in \mathbb{N}$, let $\mathcal{P}^*(Z, N, \epsilon)$ be the collection of countable or finite sets $\{(x_i, n_i)\} \subset Z \times \{N, N+1, \cdots\}$ such that $\overline{B}_{n_i}(x_i, \epsilon) \cap \overline{B}_{n_j}(x_j, \epsilon) = \emptyset, \forall i \neq j$. For each $s \in \mathbb{R}$, consider the set functions

$$m^*(Z, s, N, \epsilon) = \sup_{\mathcal{P}^*(Z, N, \epsilon)} \sum_{(x_i, n_i)} \exp(-n_i s);$$
$$m^*(Z, s, \epsilon) = \lim_{N \to \infty} m^*(Z, s, N, \epsilon);$$
$$m^{**}(Z, s, \epsilon) = \inf\left\{\sum_{i=1}^{\infty} m^*(Z_i, s, \epsilon) : \bigcup_{i=1}^{\infty} Z_i \supset Z\right\}$$

Both of these functions are non-increasing in s, and the latter takes values ∞ and 0 at all but at most one value of s. Denoting the critical value of s by

$$h^{P}(Z,\epsilon) = \inf\{s \in \mathbb{R} : m^{**}(Z,s,\epsilon) = 0\}$$
$$= \sup\{s \in \mathbb{R} : m^{**}(Z,s,\epsilon) = \infty\},\$$

leads to $m^{**}(Z, s, \epsilon) = \infty$ when $s < h^P(Z, \epsilon)$, and 0 when $s > h^P(Z, \epsilon)$.

The packing entropy of Z is $h^P(Z) := \lim_{\epsilon \to 0} h^P(Z, \epsilon)$. The limit exists because $h^P(Z, \epsilon)$ increases when ϵ decreases.

2.3 g-almost property and uniform separation property

In this section, we first present some notations to be used in the paper. Then a weak specification property and a weak expansive property are introduced. A remark about the notation is presented here for convenience.

Remark 2.2. Let (X,T) be a topological dynamical system.

- (1) If $F \subset M(X)$ is an open set, set $X_{n,F} := \{x \in X : \mathcal{E}_n x \in F\}.$
- (2) Given $\delta > 0$ and $\epsilon > 0$, two points x and y are (δ, n, ϵ) -separated if $\#\{i : d(T^ix, T^iy) > \epsilon, 0 \le i \le n-1\} \ge \delta n$. A subset E is (δ, n, ϵ) -separated if any pair of different points of E are (δ, n, ϵ) -separated.
- (3) Let F ⊂ M(X) be a neighborhood of ν, and ε > 0, and set
 N(F; n, ε) :=maximal cardinality of an (n, ε)-separated subset of X_{n,F};
 N(F; δ, n, ε) :=maximal cardinality of an (δ, n, ε)-separated subset of X_{n,F}.
- (4) Let $g : \mathbb{N} \to \mathbb{N}$ be a given nondecreasing unbounded map with the properties g(n) < n and $\lim_{n \to \infty} \frac{g(n)}{n} = 0$. The function g is called a blow-up function. Given $x \in X$ and $\epsilon > 0$; let

$$B_n(g; x, \epsilon) := \{ y \in X : \exists \Lambda \subset \Lambda_n, \#(\Lambda_n \setminus \Lambda) \leqslant g(n) \text{ and} \\ \max\{ d(T^i x, T^i y) : i \in \Lambda \} \le \epsilon \},\$$

where $\Lambda_n = \{0, 1, \cdots, n-1\}.$

Definition 2.3. ([8]) The dynamical system (X, d, T) has the g-almost product property with blow-up function g if there exists a non-increasing function $m : \mathbb{R}^+ \to \mathbb{N}$ such that for any $k \in \mathbb{N}$, any $x_1 \in X, \dots, x_k \in X$, any positive $\varepsilon_1, \varepsilon_2, \dots, \varepsilon_k$, and any integers $n_1 \ge m(\varepsilon_1), \dots, n_k \ge m(\varepsilon_k)$,

$$\bigcap_{j=1}^{k} T^{-M_{j-1}} B_{n_j}(g; x_j, \epsilon_j) \neq \emptyset,$$

where $M_0 = 0, M_i = n_1 + n_2 + \dots + n_i, i = 1, 2 \dots, k - 1.$

Definition 2.4. ([8]) The dynamical system (X, d, T) has the uniform separation property if for any η , there exist $\delta^* > 0$ and $\epsilon^* > 0$ such that for μ ergodic and any neighbourhood $F \subset M(X)$ of μ , there exists $n_{F,\mu,\eta}^*$ such that for $n \ge n_{F,\mu,\eta}^*$,

$$N(F; \delta^*, n, \epsilon^*) \ge exp(n(h(T, \mu) - \eta)),$$

where $h(T, \mu)$ is the metric entropy of μ .

Proposition 2.5. [8] Assume that (X, d, T) has the g-almost product property and the uniform separation property. For any η , there exists δ^* and $\epsilon^* > 0$ such that for $\mu \in M(X,T)$ and any neighborhood $F \subset M(X)$ of μ , there exists $n_{F,\mu,\eta}^*$, such that

$$N(F; \delta^*, n, \epsilon^*) \ge \exp(n(h(T, \mu) - \eta)), \forall n \ge n^*_{F,\mu,\eta}$$

2.4 Statement of main result

Define

$$\Lambda(y) = \begin{cases} \sup_{\mu \in M(X,T), \Xi \mu = y} h(T,\mu), & y \in \Xi(M(X,T)); \\ -\infty, & \text{otherwise.} \end{cases}$$

The following theorem is the main result of this paper.

Theorem 2.6. $(X, T, \Xi, \mathcal{E}_n, Y)$ satisfies the g-almost product property and the uniform separation property. If $C \subset Y$ is a convex and closed subset of $\Xi(M(X,T))$, then $\Delta_{equ}(C) \neq \emptyset$ and

$$h^{P}(\Delta_{equ}(C)) = h^{P}(\Delta_{sup}(C)) = \sup_{y \in C} \Lambda(y).$$

3 Proof of Theorem 2.6.

In this section, we are going to prove Theorem 2.6. The upper bound of $h^P(\Delta_{sup}(C))$ holds without extra assumption. From the second part proof of Theorem 1.1 in [10], we have

$$h^P(\Delta_{sup}(C)) \le \sup_{y \in C} \Lambda(y).$$

Now we prove the lower bound of $h^P(\Delta_{equ}(C))$. We need the following lemma.

Lemma 3.1. ([2]) Let (X, T) be a topological dynamical systems. If $K \subset X$ is non-empty and compact, then

$$h^{P}(T,K) = \sup\{ \overline{h}_{\mu}(T) : \mu \in M(X), \mu(K) = 1 \}.$$

where

$$\overline{h}_{\mu}(T) = \int \overline{h}_{\mu}(T, x) d\mu(x), \overline{h}_{\mu}(T, x) = \lim_{\epsilon \to 0} \limsup_{n \to \infty} -\frac{1}{n} \log \mu(B_n(x, \varepsilon)).$$

For any $\eta > 0$, there exists sufficiently small $\epsilon > 0$ (see below) and $p \in C$ such that

$$\sup_{q \in C} \Lambda(q) - \eta \le \Lambda(p).$$

Let $n \in \mathbb{N} \setminus \{0\}$. Since C is compact and connected, it is possible to choose $q_{n,1}, \dots, q_{n,M_n} \in C$ such that

$$C \subset \bigcup_{i=1}^{M_n} B\left(q_{n,i}, \frac{1}{n}\right),$$
$$|d'(q_{n,i} - q_{n,i+1})| \leq \frac{1}{n} \quad \forall i, |d'(q_{n,M_n} - q_{n+1,1})| \leq \frac{1}{n},$$
$$q_{n,M_n} = p \quad \forall n.$$

Let $\{\alpha_1'', \alpha_2'', \alpha_3'', \dots\} = \{q_{1,1}, q_{1,2}, \dots, q_{1,M_1}, q_{2,1}, q_{2,2}, \dots\}$; then for any $n \in \mathbb{N} \setminus \{0\}$,

$$\overline{\{\alpha_j'': j \in \mathbb{N} \setminus \{0\}, j \ge n\}} = C$$

and $\lim_{j\to\infty} d'(\alpha''_j, \alpha''_{j+1}) = 0.$

We will construct a subset $F \subset \triangle_{equ}(C)$ such that for each $x \in F$, $\{\Xi \mathcal{E}_n(x)\}$ has the same limit-point set as the sequence $\{\alpha_k''\}$ and $h^P(F) \ge \sup_{x \in C} \Lambda(x)$.

For $\frac{\eta}{2}$ and $\alpha_k'' \in C$, there exists $\alpha_k \in \Xi^{-1}C \cap M(X,T)$ such that $\Lambda(\alpha_k'') - \frac{\eta}{2} < C$ $h(T, \alpha_k)$. By Proposition 2.5, it is easy to see that for $\frac{\eta}{2} > 0$, there exist $\delta^* > 0$ and $\epsilon^* > 0$, such that for any neighborhood $F'' \subset \Xi(M(X))$ of α''_k (choose $F'' = B(\alpha_k'', \xi_k''))$, there exist $B(\alpha_k, \xi_k) \subseteq \Xi^{-1}F''$ and $n^*_{B(\alpha_k, \xi_k), \alpha_k, \frac{\eta}{2}}$ satisfying

$$N(B(\alpha_k, \xi_k); \delta^*, n, \epsilon^*) \ge \exp\left(n\left(h(T, \alpha_k) - \frac{\eta}{2}\right)\right),\tag{1}$$

where $n \ge n_{B(\alpha_k,\xi_k),\alpha_k),\frac{\eta}{2}}^*$ and ξ_k, ξ_k'' will be determined later. We choose strictly decreasing sequences $\{\xi_k\}_k, \{\xi_k''\}_k$ and $\{\epsilon_k\}_k$ such that $\lim_{k} \xi_k = 0, \lim_{k} \xi_k'' = 0$ with $\epsilon_1 < \epsilon^*$. From (1), we deduce the existence of n_k and a $(\delta^*, n_k, \epsilon^*)$ -separated subset $\Gamma_k \subseteq X_{n_k, B(\alpha_k, \xi_k)} \subseteq X_{n_k, \Xi^{-1}B(\alpha_k'', \xi_k'')}$ with

$$\sharp \Gamma_k \ge \exp\left(n_k \left(h(T, \alpha_k) - \frac{\eta}{2}\right)\right) \ge \exp\left(n_k (\Lambda(\alpha_k'') - \eta)\right).$$

We may assume that n_k satisfies

$$\delta^* n_k > 2g(n_k) + 1, \frac{g(n_k)}{n_k} \le \epsilon_k.$$

We choose a strictly increasing sequence $\{N_k\}_{k=0}^{\infty}$ with $N_0 = 0$ and $N_k \in \mathbb{N} \setminus \{0\}$ such that

$$n_{k+1} \leqslant \xi_k \sum_{j=1}^k n_j N_j$$

and

$$\sum_{j=1}^{k-1} n_j N_j \le \xi_k \sum_{j=1}^k n_j N_j.$$
(2)

We enumerate the points in the set Γ_k and consider the set $\Gamma_i^{N_i}$, $i = 1, 2, \cdots$,

Let $\underline{x}_i = (x_1^i, \cdots, x_{N_i}^i) \in \Gamma_i^{N_i}$, for any $(\underline{x}_1, \cdots, \underline{x}_k) \in \Gamma_1^{N_1} \times \cdots \times \Gamma_k^{N_k}$, by g-almost product property, we have

$$B(\underline{x}_1,\cdots,\underline{x}_k) = \bigcap_{i=1}^k \bigcap_{j=1}^{N_i} T^{-\sum_{l=0}^{i-1} N_l n_l - (j-1)n_i} B_{n_i}(g; x_j^i, \varepsilon_j)$$

is a non-empty closed set. We define ${\cal F}_k$ by

$$F_k = \bigcup \left\{ B(\underline{x}_1, \cdots, \underline{x}_k) : (\underline{x}_1, \cdots, \underline{x}_k) \in \Gamma_1^{N_1} \times \cdots \times \Gamma_k^{N_k} \right\}.$$

Note that F_k is compact and $F_{k+1} \subseteq F_k$. Define $F = \bigcap_{i=1}^{\infty} F_k$. Let $t_k = \sum_{i=1}^k n_i N_i$.

The proof of the following lemma is same as the proof of Lemma 3.2 in [9].

Lemma 3.2. Let ϵ be such that $4\epsilon = \epsilon^*$, then

(1) Let $x_i, y_i \in \Gamma_i$ with $x_i \neq y_i$. If $x \in B_{n_i}(g; x_i, \epsilon_i)$ and $y \in B_{n_i}(g; y_i, \epsilon_i)$, then

$$d_{n_i}(x,y) = \max\{d(T^jx, T^jy) : j = 0, 1, \cdots, n_i - 1\} > 2\epsilon.$$

(2) $F \subset \triangle_{equ}(C)$.

For each $(\underline{x}_1, \dots, \underline{x}_k) \in \Gamma_1^{N_1} \times \dots \times \Gamma_k^{N_k}$, we choose one point $z = z(\underline{x}_1, \dots, \underline{x}_k)$ such that $z \in B(\underline{x}_1, \dots, \underline{x}_k)$. Let L_k be the set of all points constructed in this way. ¿From Lemma 3.2, we have $\sharp L_k = \sharp \Gamma_1^{N_1} \sharp \Gamma_2^{N_2} \cdots \sharp \Gamma_k^{N_k}$. We define for each k, an atomic measure centred on L_k . Precisely, let

$$\nu_k = \sum_{z \in L_k} \delta_z.$$

We normalise ν_k to obtain a sequence of probality measure μ_k , i.e. we let

$$\mu_k = \frac{1}{\sharp L_k} \nu_k.$$

Lemma 3.3. Suppose μ is a limit point of the sequence of probability measures μ_k , then $\mu(F) = 1$.

Proof. Suppose $\mu = \lim_{k\to\infty} \mu_{l_k}$ for $l_k \to \infty$. For any fixed l and all $p \ge 0, \mu_{l+p}(F_l) = 1$ since $F_{l+p} \subset F_l$. Thus, $\mu(F_l) \ge \limsup_{k\to\infty} \mu_{l_k}(F_l) = 1$. It follows that $\mu(F) = 1$.

Lemma 3.4. Let μ be limit point of the sequence of probability measure μ_k and $\varepsilon = \frac{1}{4}\epsilon^*$. For any $x \in F$ and $\delta > 0$, there exists a increasing sequence $\{l_i\}$ with $\lim_{i \to \infty} l_i = \infty$ such that for sufficiently large *i*, we have

$$\mu(B_{l_i}(x,\epsilon)) \le e^{-l_i}(\overline{s}-\delta),$$

where $\overline{s} = \sup_{x \in C} \Lambda(x) - 2\eta$.

Proof. Choose $l_i = t_{M_1 + \dots + M_i}$. Let $\underline{s} = \inf_{x \in C} \Lambda(x) - \eta$. First we show that

$$\mu_{M_1+\dots+M_i+p}(B_{l_i}(x,\varepsilon)) \le \sharp L_{M_1+\dots+M_i}^{-1}, \forall p \in \mathbb{N} \setminus \{0\}$$

If $\mu_{M_1+\dots+M_i+p}(B_{l_i}(x,\varepsilon)) > 0$, then $L_{M_1+\dots+M_i+p} \cap B_{l_i}(x,\varepsilon) \neq \emptyset$. Let $z = z(\underline{x},\underline{y}) \in L_{M_1+\dots+M_i+p} \cap B_{l_i}(x,\varepsilon), z' = z(\underline{x}',\underline{y}') \in L_{M_1+\dots+M_i+p} \cap B_{l_i}(x,\varepsilon)$, where

$$\underline{x}, \underline{x}' \in \Gamma_1^{N_1} \times \cdots \times \Gamma_{M_1 + \cdots + M_i}^{N_{M_1 + \cdots + M_i}},$$
$$\underline{y}, \underline{y}' \in \Gamma_{M_1 + \cdots + M_i + 1}^{N_{M_1 + \cdots + M_i + 1}}, \times \cdots \times \Gamma_{M_1 + \cdots + M_i + p}^{N_{M_1 + \cdots + M_i + p}}$$

Since $d_{l_i}(z, z') \leq 2\epsilon$, from Lemma 3.2, we have $\underline{x} = \underline{x}'$. Thus we have

$$\mu_{M_1+\dots+M_i+p}(B_{l_i}(x,\varepsilon)) \\
\leq \frac{1 \times \sharp \Gamma_{M_1+\dots+M_i+1}^{N_{M_1}+\dots+M_i+1}, \times \dots \times \sharp \Gamma_{M_1+\dots+M_i+p}^{N_{M_1}+\dots+M_i+p}}{\sharp L_{M_1+\dots+M_i+p}} \\
= \frac{1}{\sharp L_{M_1+\dots+M_i}}.$$

This leads to

$$\mu(B_{l_i}(x,\varepsilon)) \leq \limsup_{k \to \infty} \mu_k(B_{l_i}(x,\varepsilon))$$

$$= \frac{1}{\sharp \Gamma_1^{N_1} \sharp \Gamma_2^{N_2} \cdots \sharp \Gamma_{M_1 + \dots + M_i}^{N_{M_1 + \dots + M_i}}}$$

$$\leq \frac{1}{\exp\{n_1 N_1 \underline{s} + n_2 N_2 \underline{s} \cdots + n_{M_1 + \dots + M_i - 1} N_{M_1 + \dots + M_i - 1} \underline{s} + n_{M_1 + \dots + M_i} \overline{N}_{M_1 + \dots + M_i} \overline{s}\}$$

$$= \exp\left\{-l_i \left(\frac{n_1 N_1 + \dots + n_{M_1 + \dots + M_i - 1} N_{M_1 + \dots + M_i - 1} \underline{s} + \frac{n_{M_1 + \dots + M_i} N_{M_1 + \dots + M_i} \overline{s}}{l_i} \overline{s}\right)\right\}.$$

It follow from (2), we have

$$\lim_{i \to \infty} \frac{n_1 N_1 + \dots + n_{M_1 + \dots + M_i - 1} N_{M_1 + \dots + M_i - 1}}{l_i} = 0.$$

$$\lim_{i \to \infty} \frac{n_1 N_1 + \dots + n_{M_1 + \dots + M_i} N_{M_1 + \dots + M_i}}{l_i} = 1.$$

Thus for sufficiently large *i*, we have $\mu(B_{l_i}(x, \epsilon) \leq e^{-l_i(\bar{s}-\delta)})$.

Applying Lemma 3.1, we have

$$h^P(F) \ge \overline{s} - \delta = \sup_{x \in C} \Lambda(x) - 2\eta - \delta.$$

Since η and δ are arbitrary, we have

$$h^{P}(\Delta_{equ}(C)) \ge h^{P}(C) \ge \sup_{x \in C} \Lambda(x).$$

Thus the proof of Theorem 2.6 is completed.

4 Application

In this section, we apply our result to the packing dimension for β -shift. Let $n = \lceil \beta \rceil$. Let $\beta > 1$ be fixed. For $t \in \mathbb{R}$, we define

$$\lfloor t \rfloor = \max\{i \in \mathbb{Z} : i \le t\}, \lceil t \rceil := \min\{i \in \mathbb{Z} : i \ge t\}.$$

Consider the β -expansion of 1,

$$1 = \sum_{i=1}^{\infty} c_i \beta^{-j},$$

which is given by the algorithm

$$r_0 = 1, c_{i+1} = \lceil \beta r_i \rceil - 1, r_{i+1} = \beta r_i - c_{i+1}, \quad i \in \mathbb{Z}_+.$$

For sequences $\{a_i\}_{i\geq 1}$ and $\{b_i\}_{i\geq 1}$ the lexicographical order is defined by $\{a_i\} < \{b_i\}$ if and only if for the least index i with $a_i \neq b_i$, $a_i < b_i$. The β -shift is the subshift of the full shift on the alphabet with n characters, $A := \{0, 1, \dots, n-1\}$, which is given by

$$X^{\beta} = \{\omega = \{\omega_i\}_{i \ge 1} : \omega_i \in A, T^k\{\omega_i\} \le \{c_i\} \forall k \in \mathbb{Z}_+\},\$$

where $T(\omega_1, \omega_2, \omega_3, \cdots) = (\omega_2, \omega_3, \cdots)$. Pfister and Sullivan [8] proved that (X^{β}, T) satisfies g-almost product property and uniform separation property.

Endow X^{β} with the metric $d(x, y) = e^{-n}$ for $x = (x_i)_{i=1}^{\infty}$ and $y = (y_i)_{i=1}^{\infty}$, where *n* is the largest integer such that $x_i = y_i, 1 \leq i \leq n$. It is easy to check that for any $Z \subset X^{\beta}$, $h^P(Z) = \dim_P(Z)$, where $\dim_P(Z)$ denotes the packing dimension of Z. Hence, if C is a closed and convex subset of $\Xi(M(X^{\beta}, T))$, then

$$\dim_P \left\{ x \in X^\beta | A(\Xi L_n x) = C \right\} = \dim_P \left\{ x \in X^\beta | A(\Xi L_n x) \subset C \right\} = \sup_{y \in C} \Lambda(y).$$

References

- E. Chen, T. Küpper and L. Shu, Topological entropy for divergence points, *Ergodic Theory Dynam. Systems*, 25, (2005), 1173 - 1208.
- [2] D.J. Feng and W. Huang, Variational principles for topological entropies of subsets, *Journal of Functional Analysis*, 263(8), (2012), 2228 - 2254.
- [3] L. Olsen, Divergence points of deformed empirical measures, Mathematical Research Letters, 9, (2002), 1 - 13.
- [4] L. Olsen, Multifractal analysis of divergence points of deformed measure theoretical Birkhoff averages, J. Math. Pures Appl., 82, (2003), 1591 -1649.
- [5] L. Olsen, Multifractal analysis of divergence points of deformed measure theoretical Birkhoff averages. III, Aequationes Math., 71, (2006), 29 - 58.
- [6] L. Olsen, Multifractal analysis of divergence points of deformed measure theoretical Birkhoff averages. IV: Divergence points and packing dimension, Bull. Sci. Math., 132, (2008), 650 - 678.
- [7] L. Olsen and S. Winter, Normal and non-normal points of self-similar sets and divergence points of self-similar measures, *Jour. London Math. Soc.*, 67, (2003), 103 - 122.
- [8] C.E. Pfister and W.G. Sullivan, On the topological entropy of saturated sets, Ergodic Theory Dynam. Systems, 27, (2007), 929 - 956.
- [9] X. Zhou and E. Chen, Multifractal analysis for the historic set in topological dynamical systems, *Nonlinearity*, 26, (2013), 1975 - 1997.
- [10] X. Zhou, E. Chen and W. Cheng, Packing entropy and divergence points, Dyam. Systems, 27(3), (2012), 387 - 402.